

Cortex

Birds of a Feather



SIGGRAPH 2011

Overview

John Haddon, Image Engine

Lighting & rendering & fur

Andrew Kaufman, Image Engine

Crowd animation & rendering

Carsten Kolve, Dr. D Studios

Cool things Dan has been doing

Dan Bethell

Nuke integration

Paolo Berto, Jupiter Jazz

Oh No, Not Crowds Again

Ollie Rankin, the facility currently known as Method

Starting up with Cortex

Johannes Saam, Fuel

Future directions

John Haddon, Image Engine

Overview

John Haddon, Image Engine

What is Cortex?

- A foundation framework for VFX software development
- Cross application capable
- Well tested
- Open source
- An opportunity to collaborate

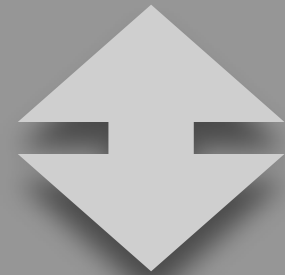
Python

Maya

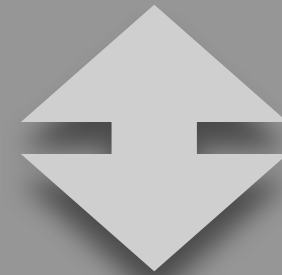
Nuke

Houdini

RenderMan



Host layers



Parameters, Ops, Procedurals

Data, Primitives, IO

STL, Boost, Imath, Additional Math

Parameters

- Provide input
- Strongly typed
- Perform validation
- Allow introspection
- Are mapped to and from host inputs
- Values are always native Cortex types

```
m_meshParameter = new MeshPrimitiveParameter(
    "mesh",
    "The mesh to distribute points over.",
    new MeshPrimitive()
);

m_densityParameter = new FloatParameter(
    "density",
    "The density of the distributed points.",
    100.0
);

m_offsetParameter = new V2fParameter(
    "offset",
    "A UV offset for the PointDistribution",
    Imath::V2f( 0, 0 )
);

m_densityPrimVarNameParameter = new StringParameter(
    "densityPrimVarName",
    "The primitive variable to use as a density threshold.",
    "density"
);

m_pRefPrimVarNameParameter = new StringParameter(
    "pRefPrimVarName",
    "The primitive variable that holds the reference positions.",
    "Pref"
);

m_uPrimVarNameParameter = new StringParameter(
    "uPrimVarName",
    "The primitive variable for u coordinates.",
    "s"
);
```

```
self.meshParameter = IECore.MeshPrimitiveParameter(  
    "mesh",  
    "The mesh to distribute points over.",  
    IECore.MeshPrimitive()  
)  
  
self.densityParameter = IECore.FloatParameter(  
    "density",  
    "The density of the distributed points.",  
    100.0  
)  
  
self.offsetParameter = IECore.V2fParameter(  
    "offset",  
    "A UV offset for the PointDistribution",  
    IECore.V2f( 0, 0 ),  
)  
  
self.densityPrimVarNameParameter = IECore.StringParameter(  
    "densityPrimVarName",  
    "The primitive variable to use as a density threshold.",  
    "density"  
)  
  
self.pRefPrimVarNameParameter = IECore.StringParameter(  
    "pRefPrimVarName",  
    "The primitive variable that holds the reference positions.",  
    "Pref"  
)  
  
self.uPrimVarNameParameter = IECore.StringParameter(  
    "uPrimVarName",  
    "The primitive variable for u coordinates.",  
    "s"  
)  
)
```



List Selected Focus Attributes Show Help

visualiser

visualiserShape

pointDistribution

initialShadingGroup

ieOpHolderNode: pointDistribution

Focus

Presets

Show

Hide

▶ Class

▼ Parameters

Mesh pTorusShape1.outMesh

Density 0.1000

Offset 0.0000 0.0000

Density Prim Var Name density

P Ref Prim Var Name Pref

U Prim Var Name s

V Prim Var Name t

▶ Extra Attributes

Notes: pointDistribution

Select

Load Attributes

Copy Tab

Close

ieOpHolder1 x Take List x +

obj geol

Cortex Op ieOpHolder1

Category: pri... Class: po... Ve... 6

Reload

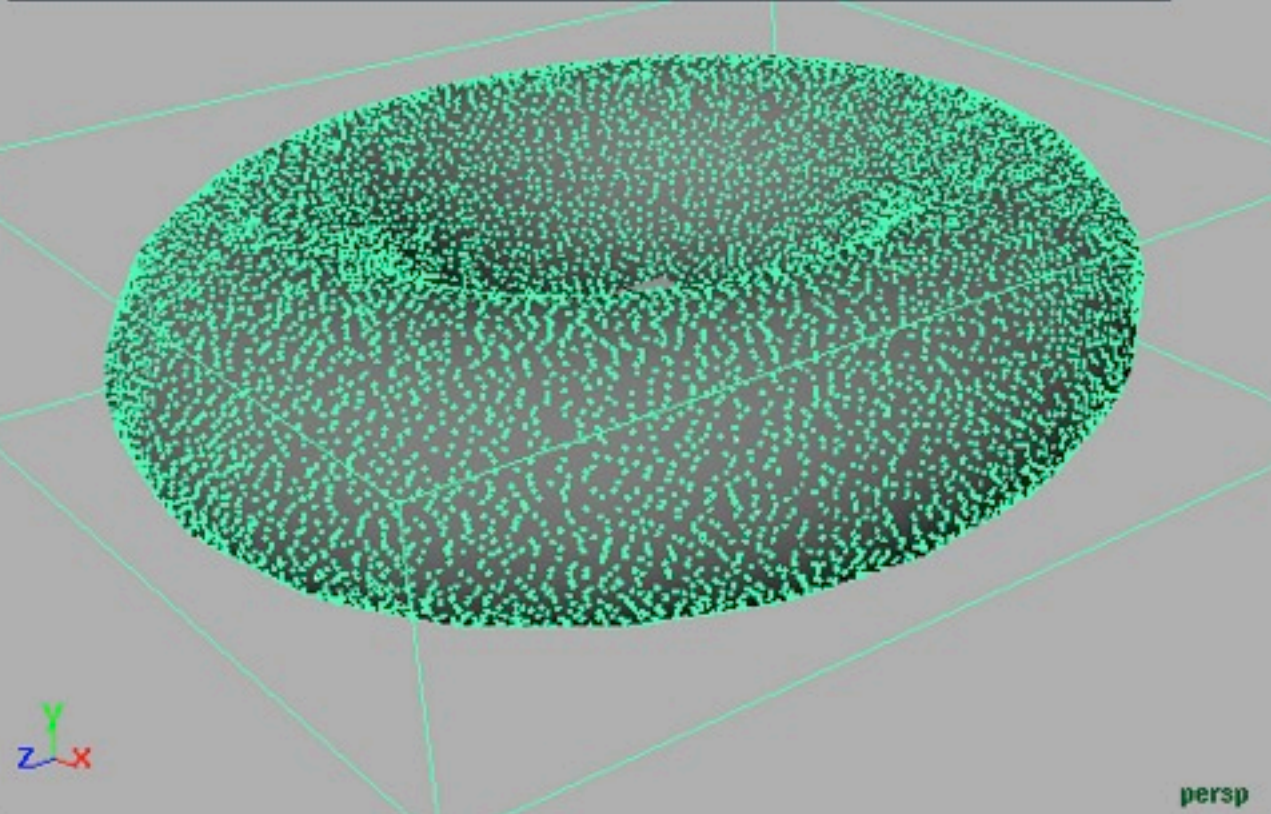
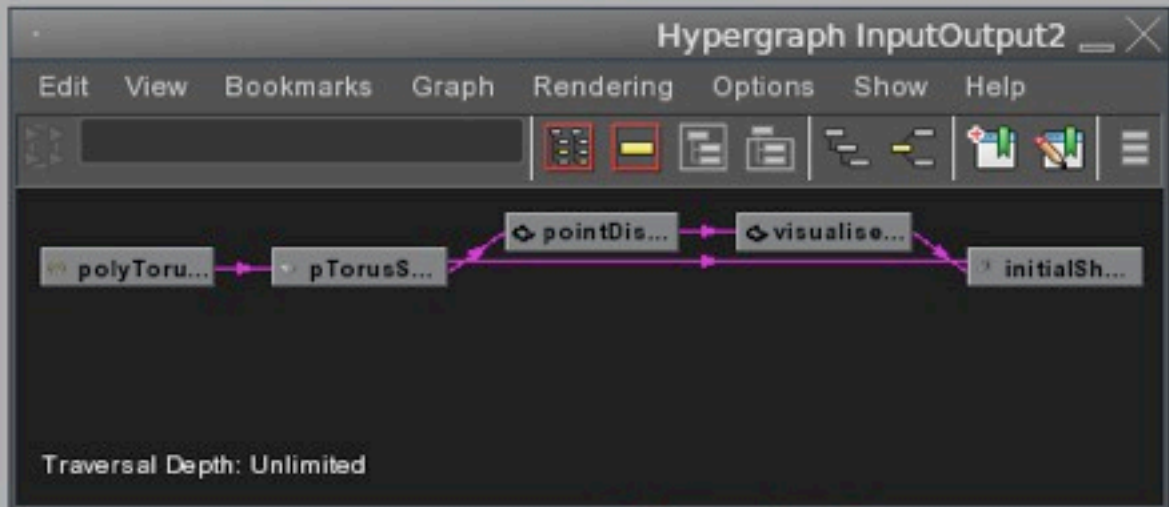
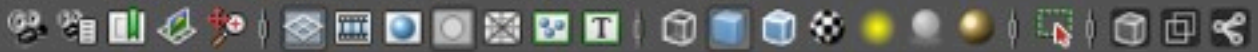
Parameters

Density	10	
Offset	0	0
Density Prim Var N...	density	
P Ref Prim Var Name	Pref	
U Prim Var Name	s	
V Prim Var Name	t	

```
-mesh read:myMesh.cob -density 10 -offset 0 0
```


Ops

- Glorified functions
- Take parameter inputs and compute a result
- Result described by output parameter
- Much Cortex functionality implemented as Ops
- Implemented in Python or C++



Attribute Editor

List Selected Focus Attributes Show Help

visualiser visualiserShape pointDistribution initialShadingGroup

ieOpHolderNode: pointDistribution

Focus Presets Show Hide

Class

Parameters

Mesh pTorusShape1.outMesh

Density 0.1000

Offset 0.0000 0.0000

Density Prim Var Name density

P Ref Prim Var Name Pref

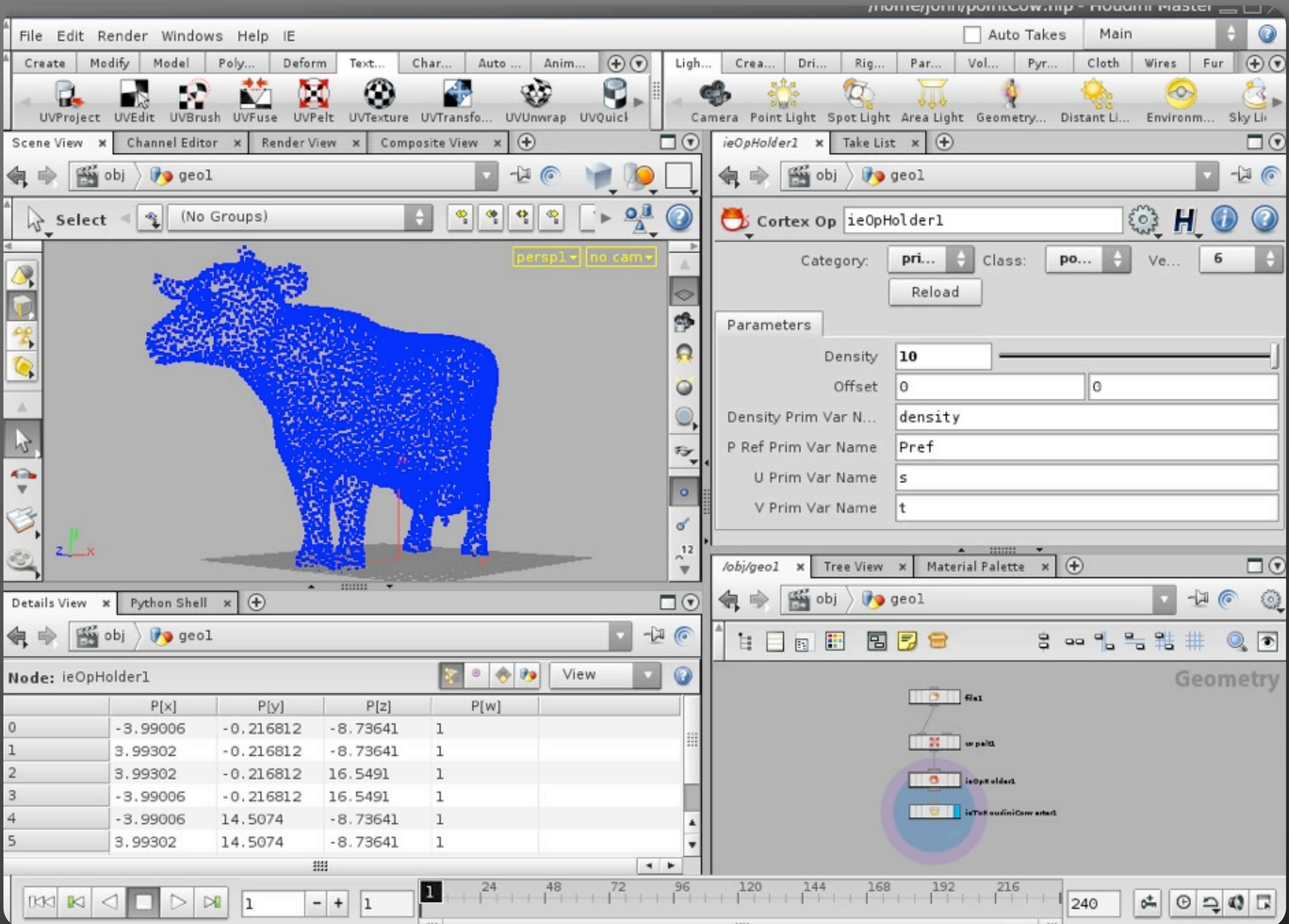
U Prim Var Name s

V Prim Var Name t

Extra Attributes

Notes: pointDistribution

Select Load Attributes Copy Tab Close



Node: ieOpHolder1

	P[x]	P[y]	P[z]	P[w]
0	-3.99006	-0.216812	-8.73641	1
1	3.99302	-0.216812	-8.73641	1
2	3.99302	-0.216812	16.5491	1
3	-3.99006	-0.216812	16.5491	1
4	-3.99006	14.5074	-8.73641	1
5	3.99302	14.5074	-8.73641	1

Cortex Op ieOpHolder1

Category: pri... Class: po... Ve... 6

Reload

Parameters

Density: 10

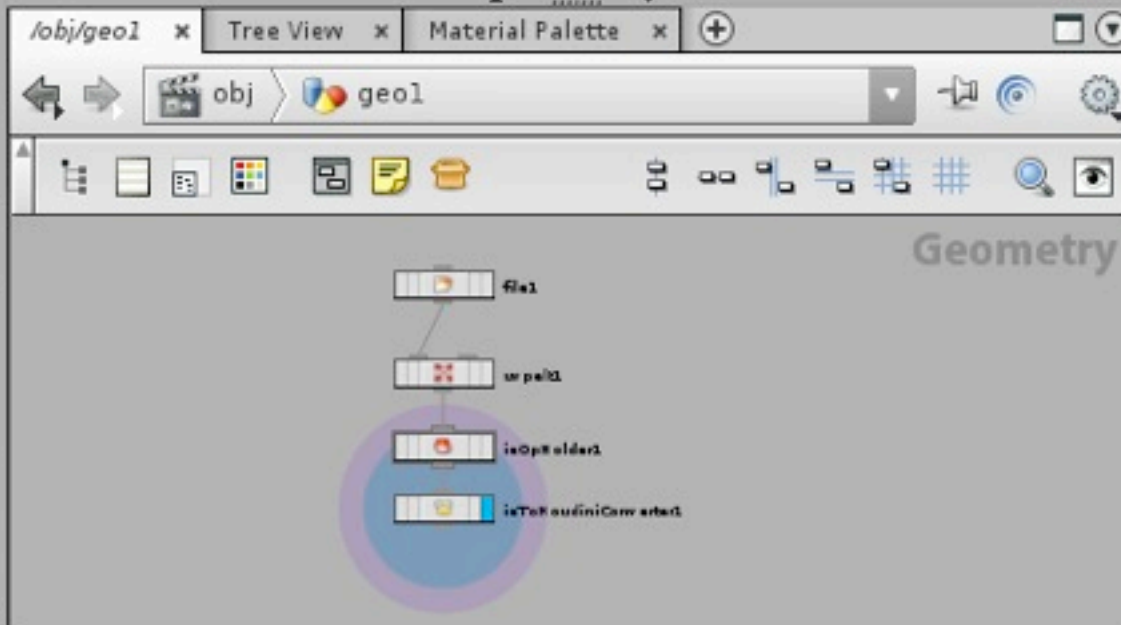
Offset: 0 0

Density Prim Var N...: density

P Ref Prim Var Name: Pref

U Prim Var Name: s

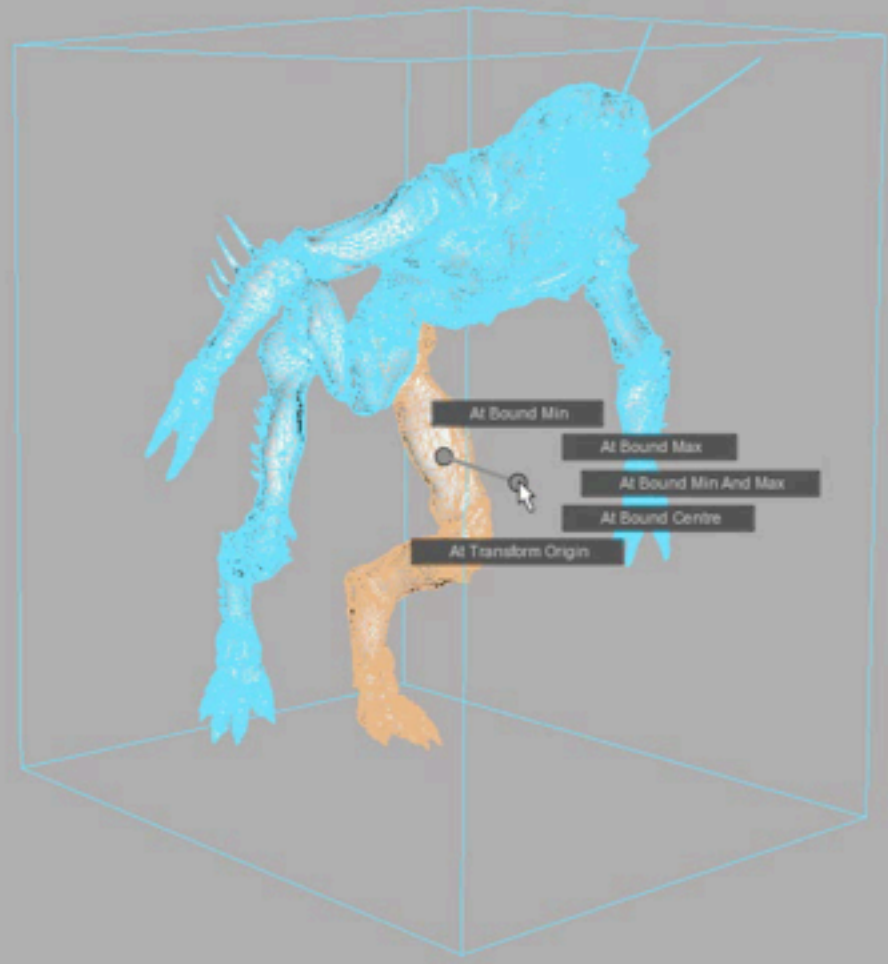
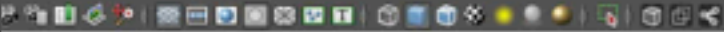
V Prim Var Name: t



Procedurals

- Deferred (render time) geometry creation
- “Black Box”
- Inputs described as parameters
- Output defined by calls to a renderer backend
- Backends provide an abstraction to allow support for multiple renderers
- Implemented in Python or C++

```
class SimpleProcedural( IECore.ParameterisedProcedural ) :  
  
    ...  
  
    def doBound( self, args ) :  
  
        result = IECore.Box3f()  
        for f in glob.glob( args["directory"].value + "/*.cob" ) :  
            o = IECore.CachedReader.defaultCachedReader().read( f )  
            result.extendBy( o.bound() )  
  
        return result  
  
    def doRender( self, renderer, args ) :  
  
        for f in glob.glob( args["directory"].value + "/*.cob" ) :  
            with IECore.AttributeBlock( renderer ) :  
                renderer.setAttribute(  
                    "name",  
                    IECore.StringData( os.path.basename( f )  
                )  
                o = IECore.CachedReader.defaultCachedReader().read( f )  
                o.render( renderer )
```



vertCacheProceduralShape sme1 initialShadingGroup
ieProceduralHolder: vertCacheProceduralShape
Focus Presets Show Hide

Class
Display
 GI Preview Draw Bound
 Coordinate Systems Transparent

Parameters
Object Directory orkspaces/Files/cjExample/cjModel
Animation Sequence iple/animation/Cache/002/cj_#####.fo
Frame 379.0000

Render Stats
Extra Attributes

Notes: vertCacheProceduralShape

Select Load Attributes Copy Tab

Lighting & Rendering

Andrew Kaufman, Image Engine

Lighting and Rendering

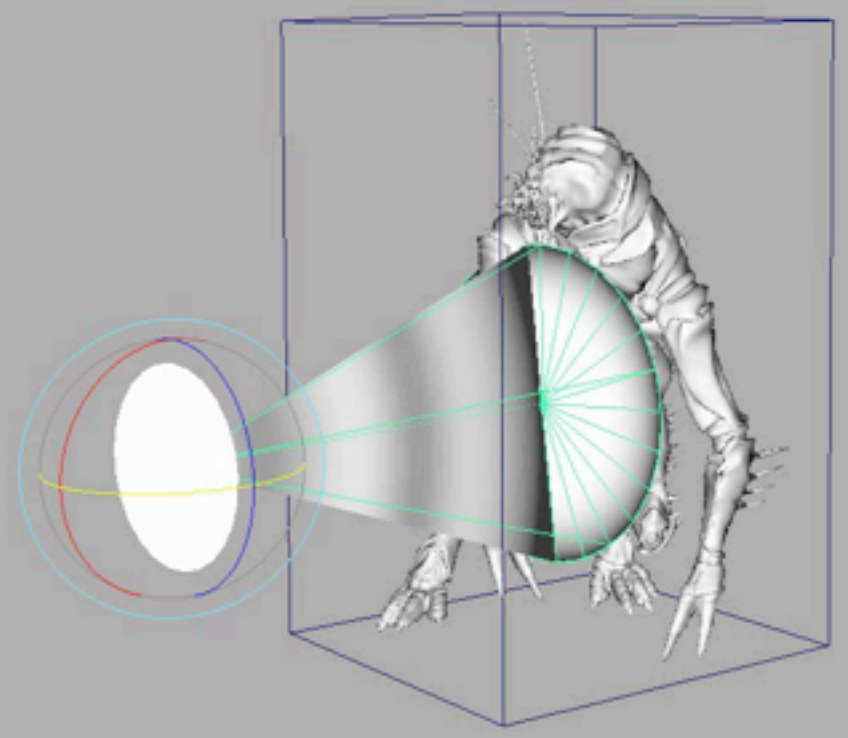
- Light in Maya, render in 3delight
- Use the 3delight plugin for rib generation. But...
- Geometry generated as procedurals
- Shading specified by procedurals
- Lights are custom

Geo caching

- Models stored in cob files (one per shape)
- Animation stored in fio files
 - Generally use vertex or transform caches
 - Could cache any PrimitiveVariables
- Effects exported from Houdini as cob/fio.
- Efficient loading/interpolation using InterpolatedCache

A modular procedural

- ClassParameters and ClassVectorParameters
 - Dynamically add functionality
- Geometry passed through stack of user defined modifiers
 - Shader assignment
 - Animation
 - Attributes etc...



spotLight spotLightShape timeToUnitConversion2

Color History

A color selection interface featuring a color history strip with a grid of color swatches, a color wheel, and three sliders for Hue (H: 0), Saturation (S: 0.000), and Value (V: 1.000). The color wheel is currently set to a red color.

Specular 1.0000

Specular Size 1.0000

Category default

Group 0

Scale 100.0000

Scale Light Disk 1.0000

Emt Photon

Shadow Mode Off

- Ray Traced Shadows
- Shadow Map Shadows
- Decay
- Radial Falloff
- Gebo

Extra Attributes

Notes: spotLightShape

Select Load Attributes Copy Tab

Bits and bobs

- Simple subsurface
- Socket display
- Spherical Harmonic lighting
- Median cut algorithm dome lighting
- Environment convolution
-

Crowd Animation & Rendering

Carsten Kolve, Dr. D Studios

Fur at Image Engine

Andrew Kaufman, Image Engine

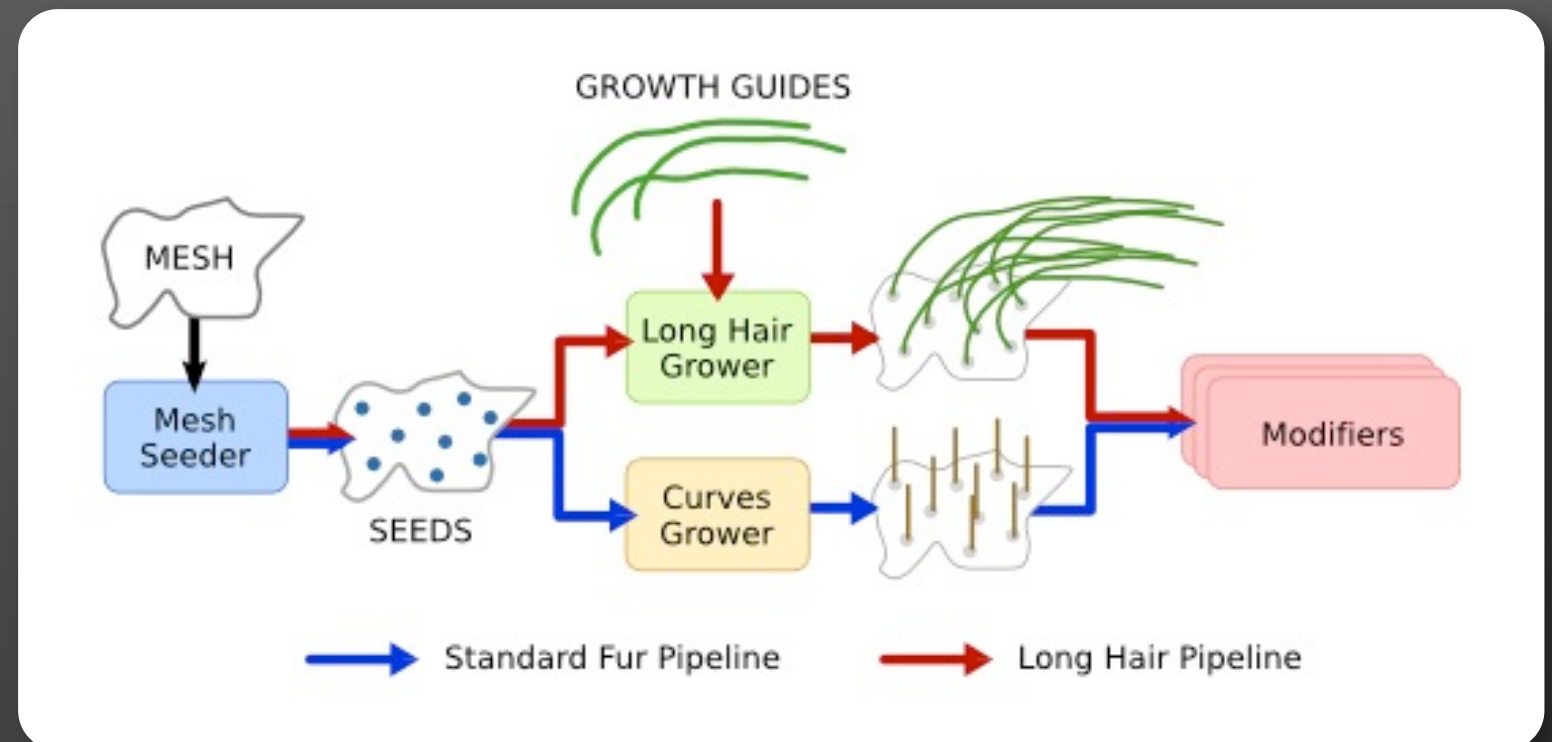


THE TWILIGHT SAQA: ECLIPSE

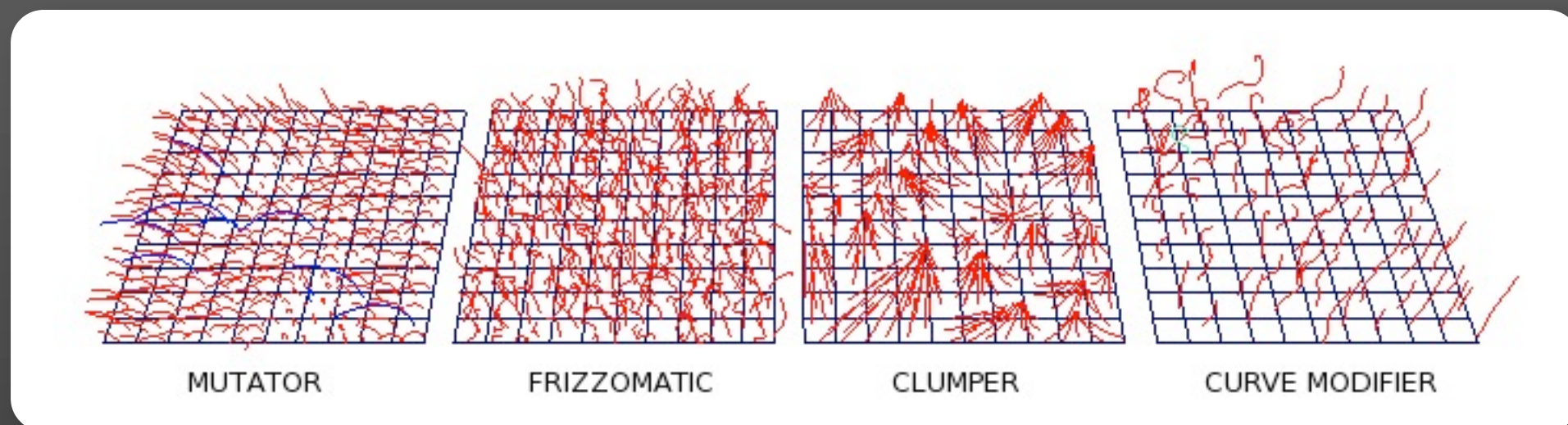
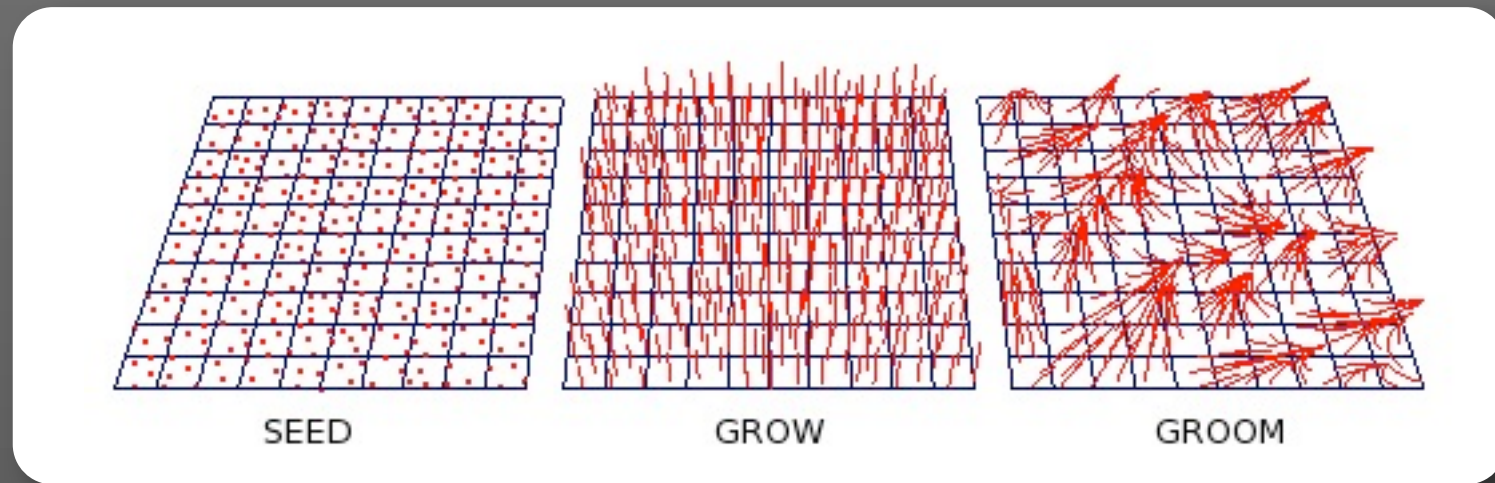
TM & © 2010 Summit Entertainment, LLC. All Rights Reserved.

Fur System

- Component of standard procedurals
- Implemented in C++
- Multi-threaded
- Groom and light in Maya*

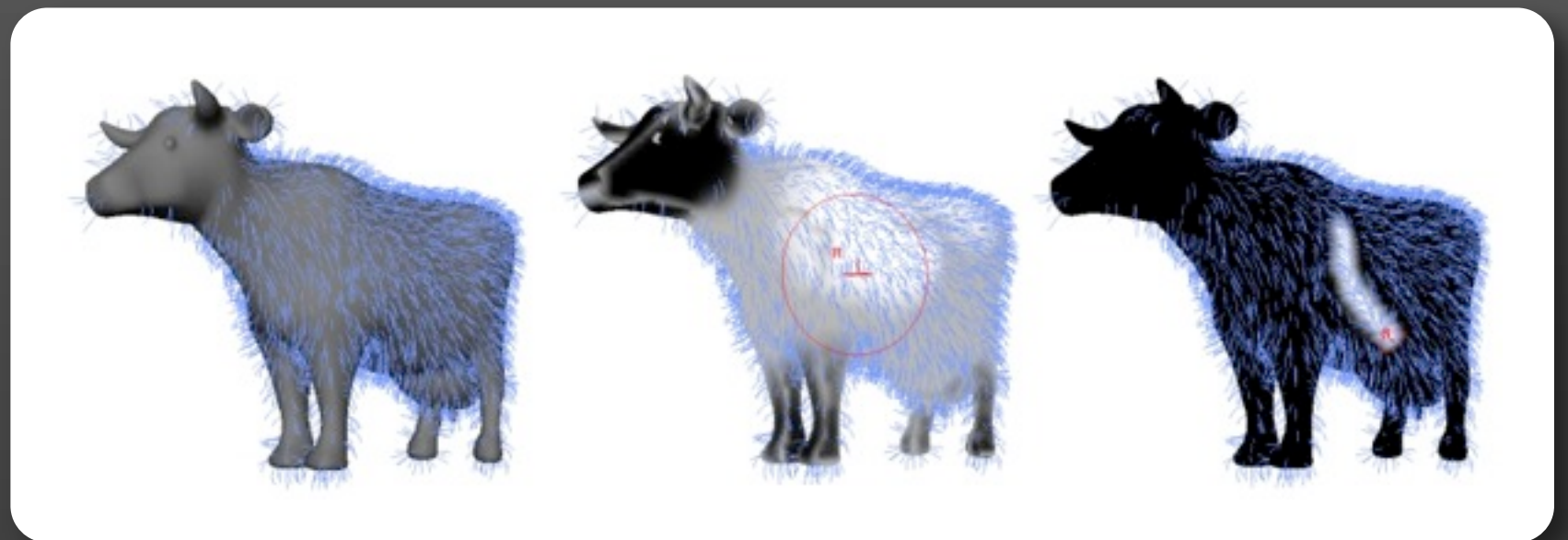


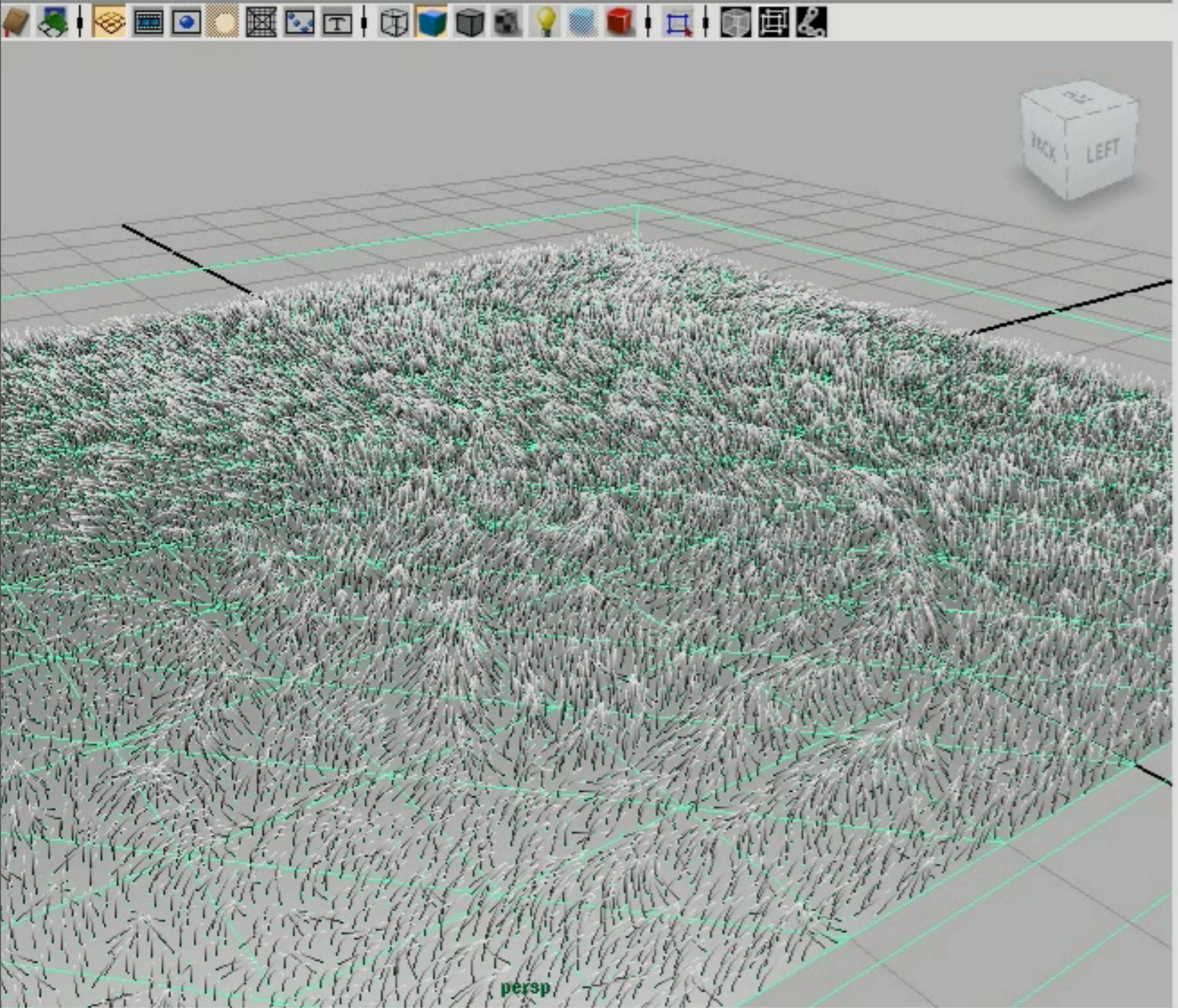
Main Components



Interactive Grooming

- Texture parameters give spatially varying control
- Vertex and image textures painted interactively
- RSL Shaders provide procedural texture inputs
 - Evaluated using 3delight Sx API
 - Reuse shaders from layered shading system





proceduralHc modularProceduralShape

- Change Me
- Groomer
- Clumper
- Ribbon Clumper

Clump Radius

Percentage

Attraction

Attraction Variation

Falloff

Jitter

Clump Volume

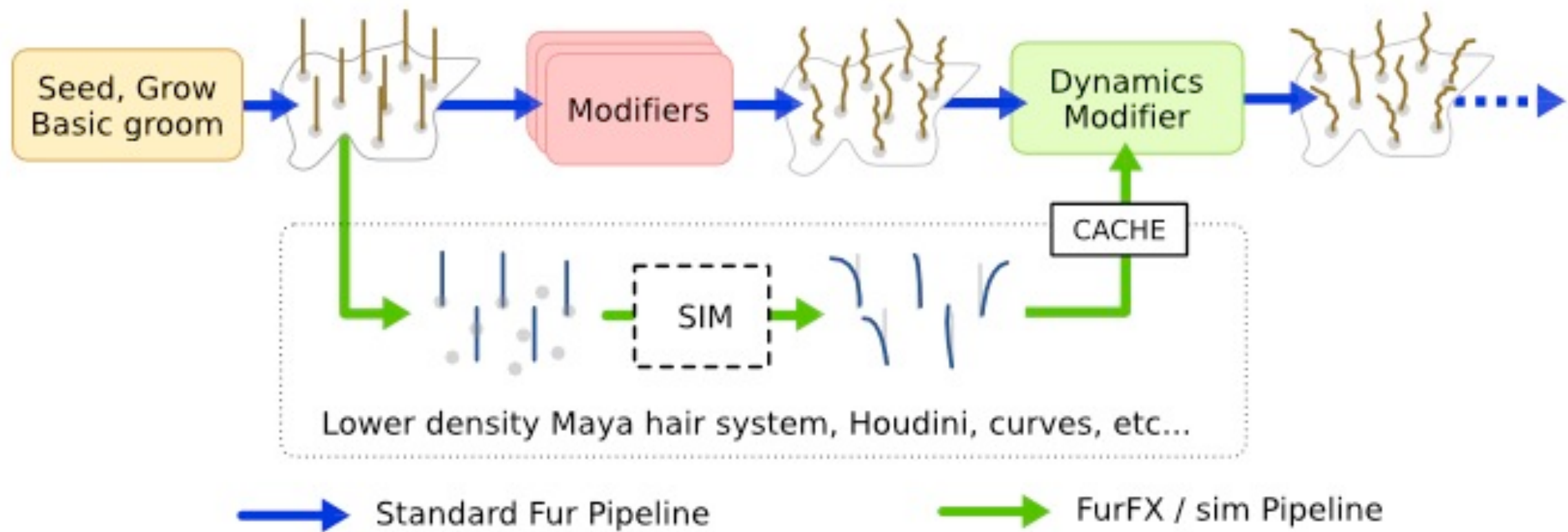
Preserve Length

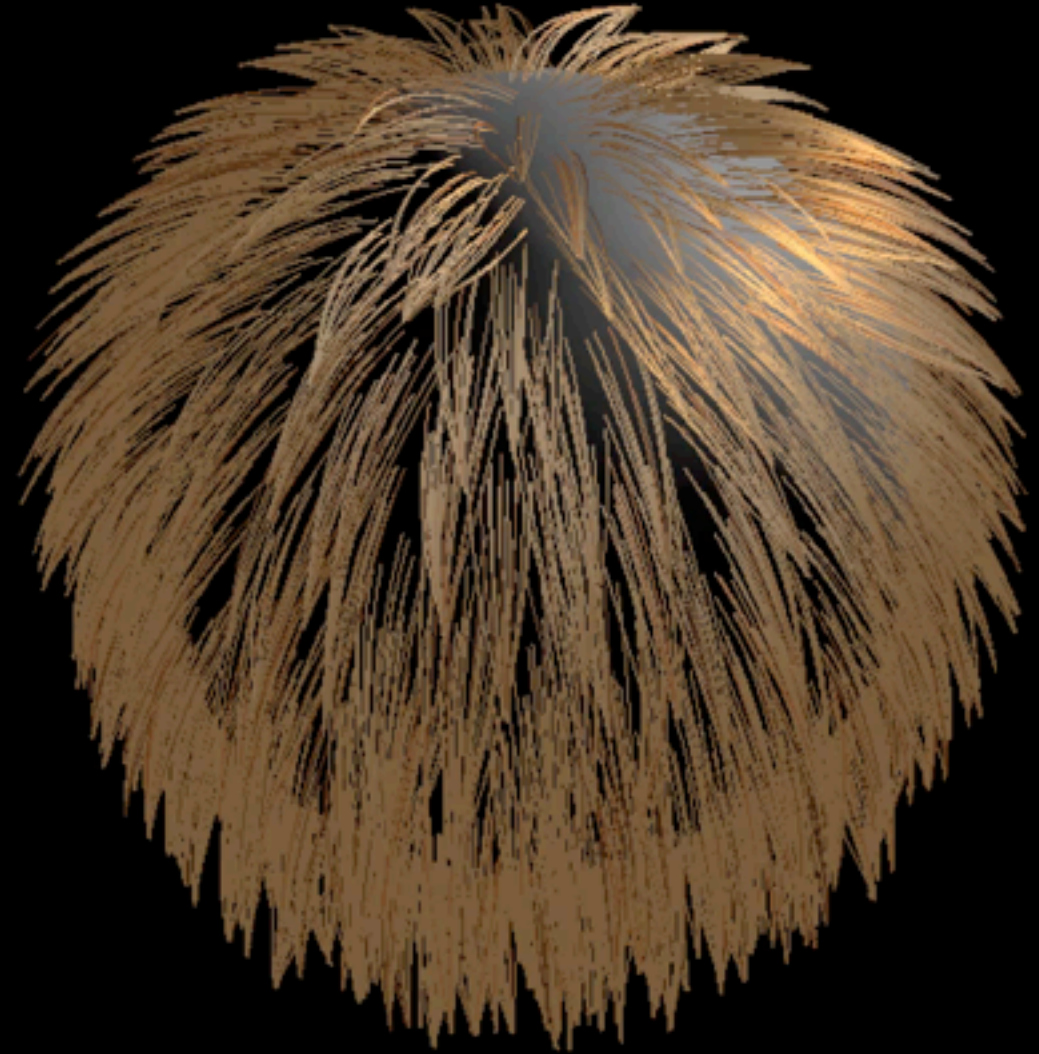
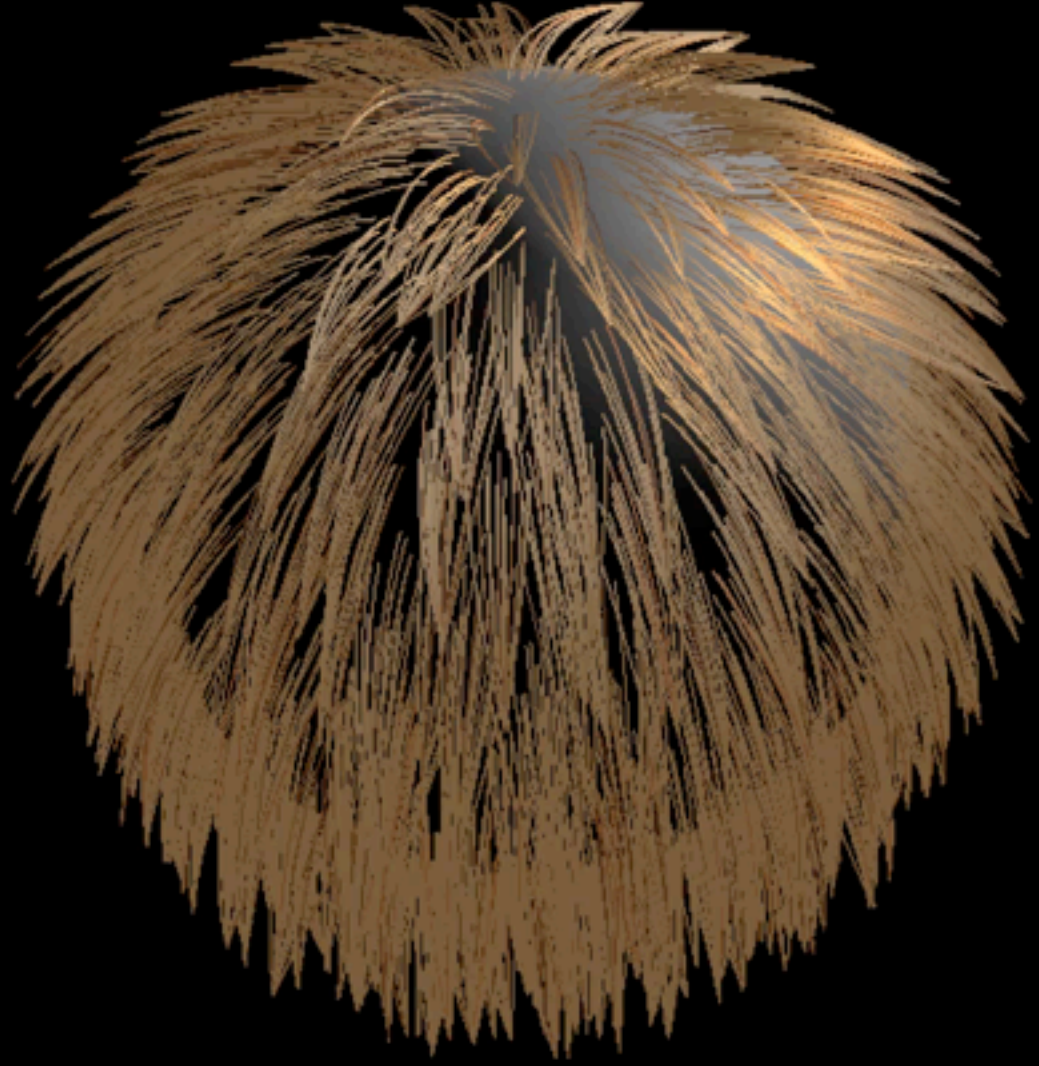
Affects Normals Modifier

Profile

Notes: modularProceduralShape

Dynamics

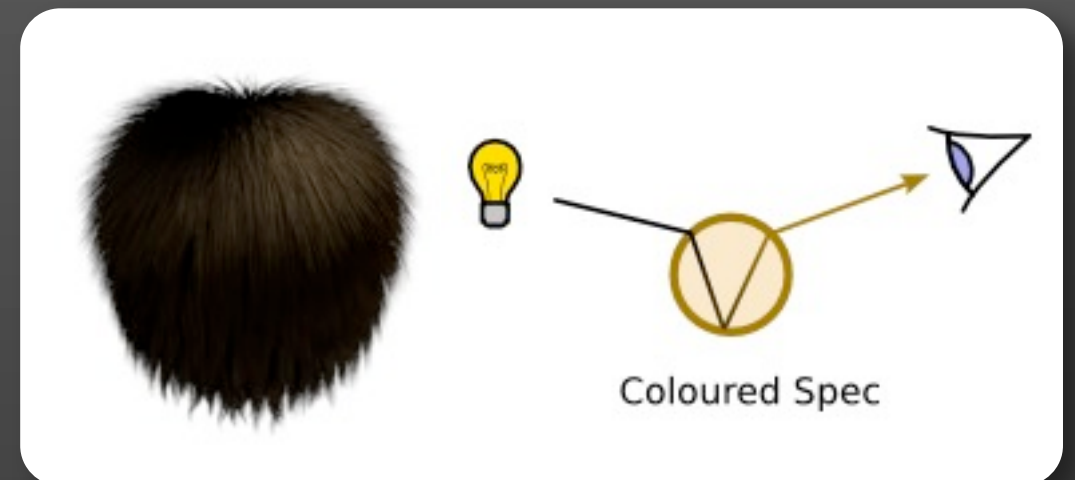
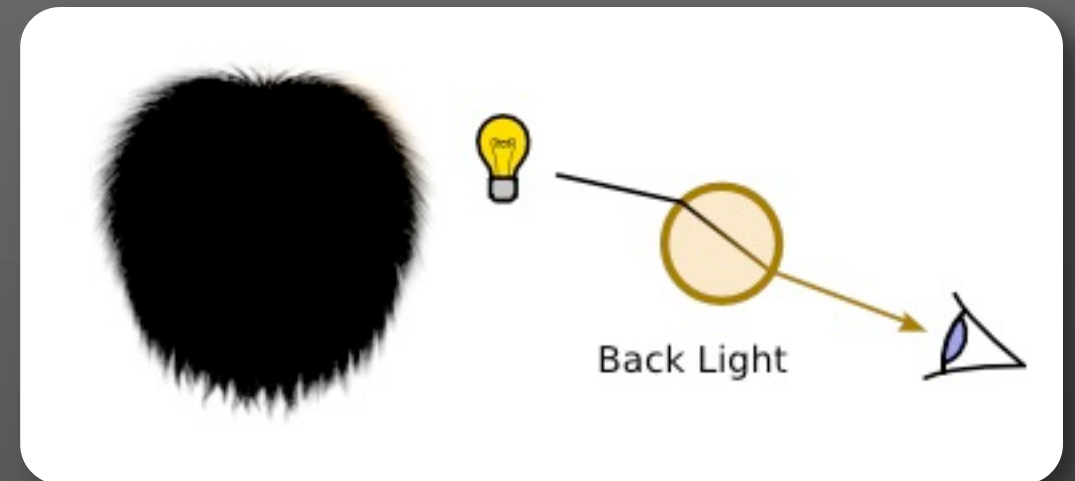
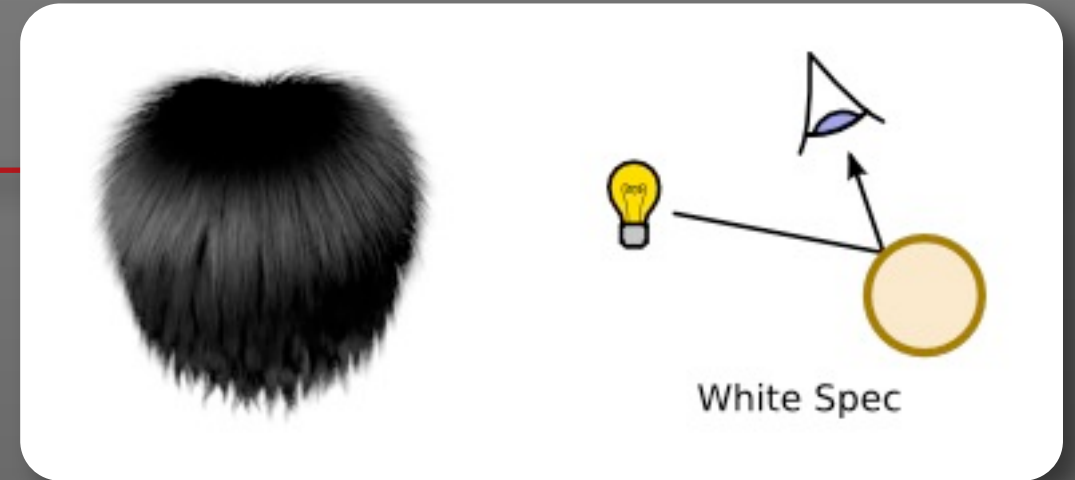


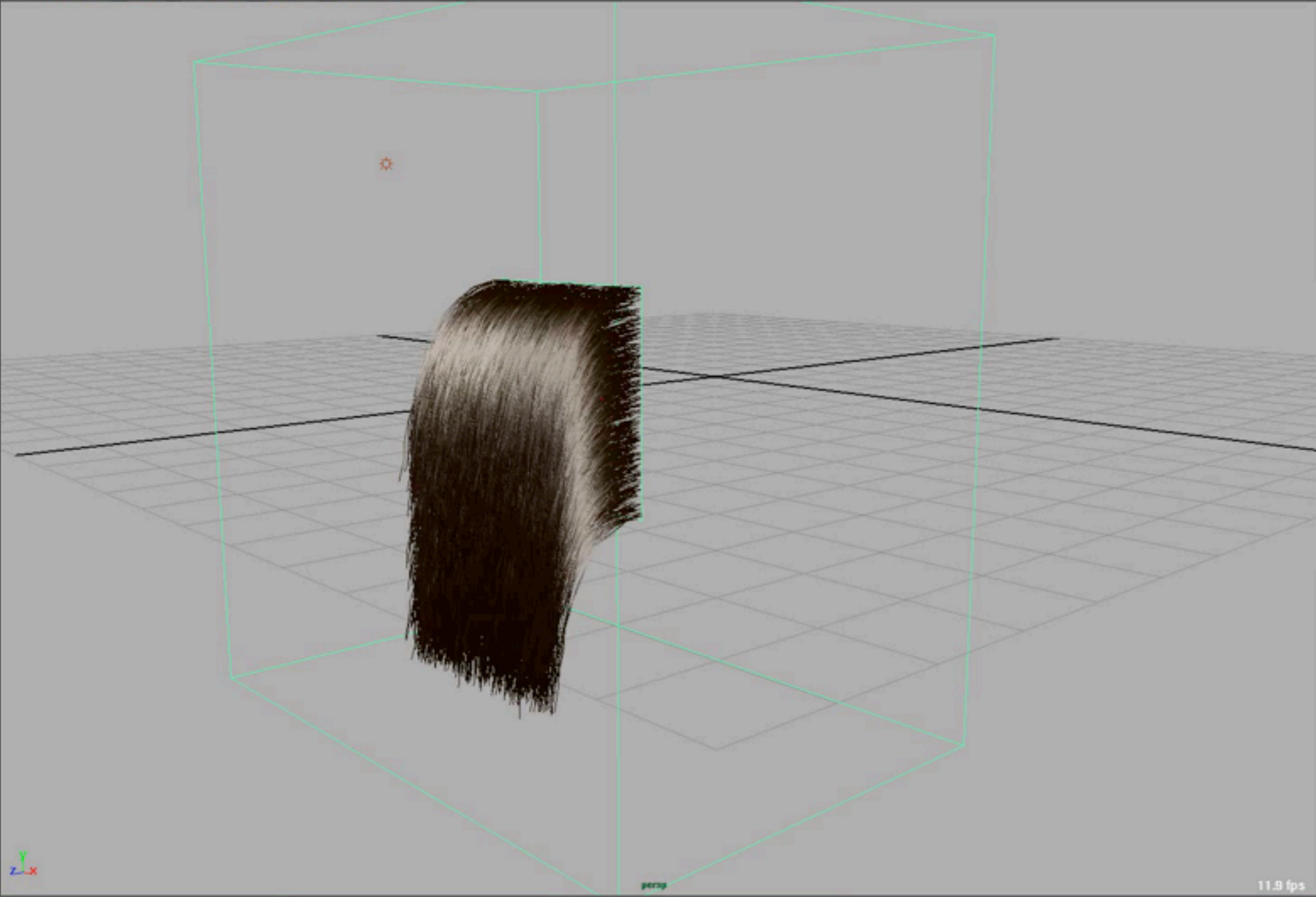




Shading

- Marschner Hair Model
- RSL for final frames
- OpenGL for preview
- Lots of deep shadows
- Experimented with SH





shadedFurExample shadedFurExampleShape initialShadingGroup

ieProceduralHolder: shadedFurExampleShape

Focus Presets Show Hide

Class

Display

Parameters

Mesh Not connected

Diffuse 0.4000

White Spec 2.5000

Backlight 0.9000

Coloured Spec 1.0000

Marschner Parameters

Color

Refraction 2.1507

Eccentricity 1.0000

Shift R -8.0000

Width R 10.0000

Shift TT 4.0000

Width TT 5.0000

Shift TRT 12.0000

Width TRT 20.0000

Oiler 1.0000

Caustic Width 20.0000

Caustic Fade 0.2000

Caustic Limit 0.5000

Hair

Length 4.0000

Count 5000

Frizz 0.1000

Gravity 1.0000

Render Stats

Extra Attributes

Notes: shadedFurExampleShape

Select Load Attributes Copy Tab



testShots_walkCycle
testShots_walkCycle comp v158

image engine
VISUAL EFFECTS FOR FILM

vera
2010-04-21



Wolf Test

testShots_walkCycle_comp_comp_native_v024.####.dpx

0125
0001-0240

image engine
VISUAL EFFECTS FOR FILM



"Twilight: Eclipse" Wolf Shots

Cool Things Dan Has Been Doing™

Carsten Kolve, Dr. D Studios

Making Tools with Cortex

(or How Cortex Makes It Easy To Do Cool Stuff)

danbethell@gmail.com

- Overview
 - Why use Cortex to develop Tools?
- Development
 - How do we write Tools with Cortex?
 - How do we build Tools against Cortex?
 - How do we deploy our Tools?
- Examples

Why use Cortex?

- Foundation of Core Libraries:
 - Geometry.
 - Rendering.
 - Algorithms.
 - I/O.
 - ...

- Multiple Application Support:

- Houdini.

- Maya.

- Nuke.

- Gaffer.

- ...

- Unified plugin interface:
 - Parameters.
 - Data passing mechanisms.
 - Python Scriptability.
 - ...

Writing Plugins

- Include Cortex Headers
 - Just the ones you need!

```
#include <IECore/Op.h>  
#include <IECore/CompoundParameter.h>  
#include <IECore/NumericParameter.h>  
#include <IECore/MeshPrimitive.h>
```

- Write Tools as Modular Components:
 - Inherit from IECore::Op

```
#include <IECore/Op.h>
#include <IECore/CompoundParameter.h>

class MyOp : public IECore::Op
{
    public:
        IE_CORE_DECLARERUNTIMETYPEEXTENSION( MyOp, MYOP_ID, IECore::Op );
        MyOp();
        virtual ~MyOp();

    protected:
        virtual IECore::ObjectPtr doOperation(
            const IECore::CompoundObject *operands );
}
```


Building Plugins

- Build against your Cortex:
 - Same compiler!
 - Same libraries!
 - Same applications!

- Made easy by PkgConfig:
 - `$INSTALL_PREFIX/lib/pkgConfig/cortex.pc`
 - Set the `PKG_CONFIG_PATH` environment variable.
- Example using CMake:

```
pkg_check_modules( Cortex REQUIRED cortex )

include_directories( ${Cortex_INCLUDE_DIRS} )
link_directories( ${Cortex_LIBRARY_DIRS} )
target_link_libraries( MyPlugin ${Cortex_LIBRARIES} )
```

Deploying Plugins

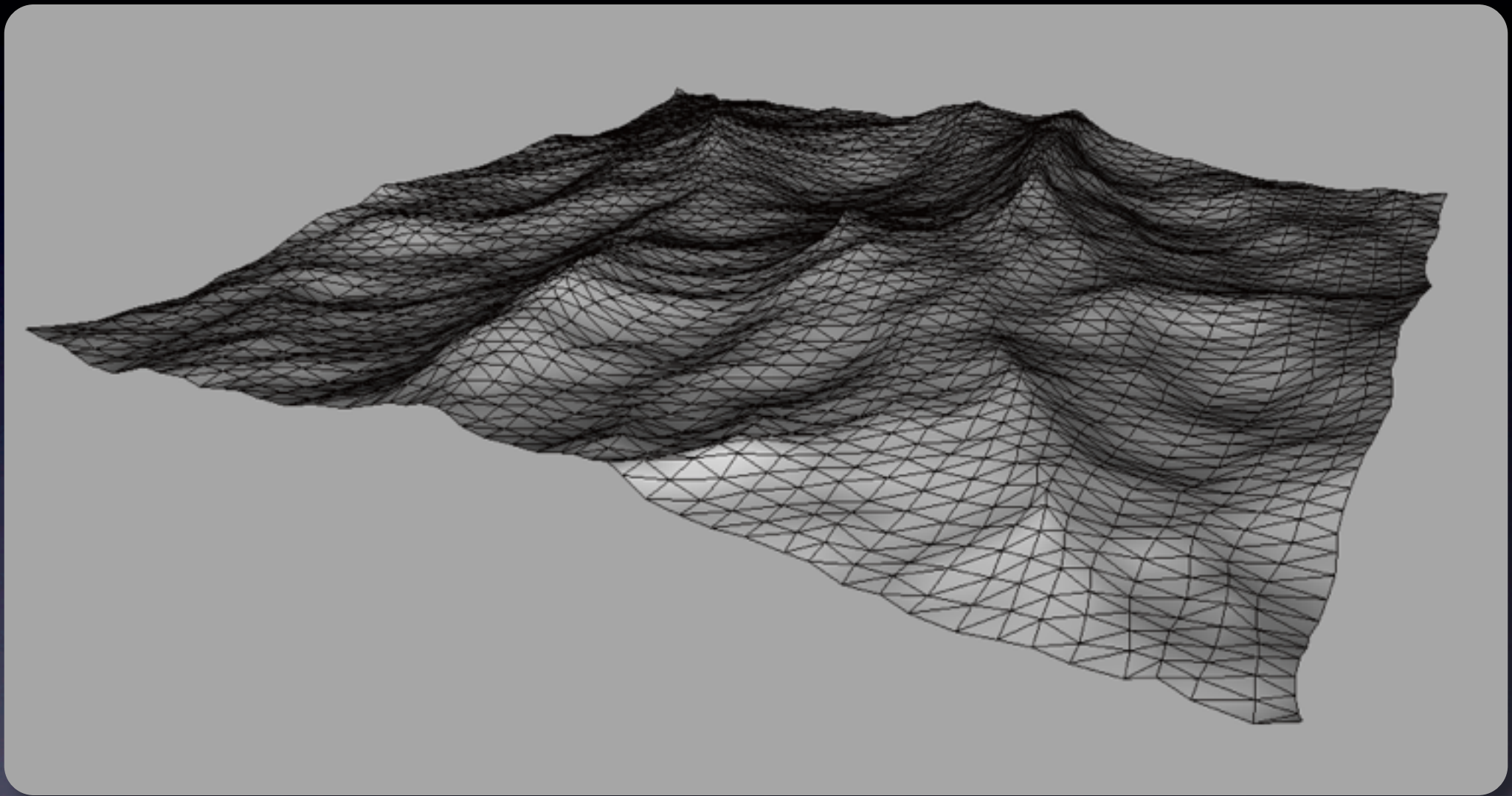
- Cortex Environment Variables:
 - `$IECORE_OP_PATHS`
 - `$IECORE_PROCEDURAL_PATHS`
- Install an Op stub for C++ Plugins:
 - `$OP_PATH/MyPlugin/MyOp/MyOp-1.py`

```
import os, sys
sys.path.append( os.path.dirname( __file__ ) )

from MyPlugin import MyOp
```


Examples

Cortex Ocean



Port of Houdini Ocean Toolkit to Cortex

- Port of existing code to Cortex.
 - Houdini Ocean Toolkit by Drew Whitehouse
 - <http://code.google.com/p/houdini-ocean-toolkit/>

- Ported as a Cortex ModifyOp:
 - Just implement ::modify()

```
class OceanOp : public ModifyOp
{
    public:
        IE_CORE_DECLARERUNTIMETYPEEXTENSION( OceanOp, 666001, ModifyOp );
        OceanOp();
        virtual ~OceanOp();

    protected:
        virtual void modify( Object *input, const CompoundObject *operands );
}
```

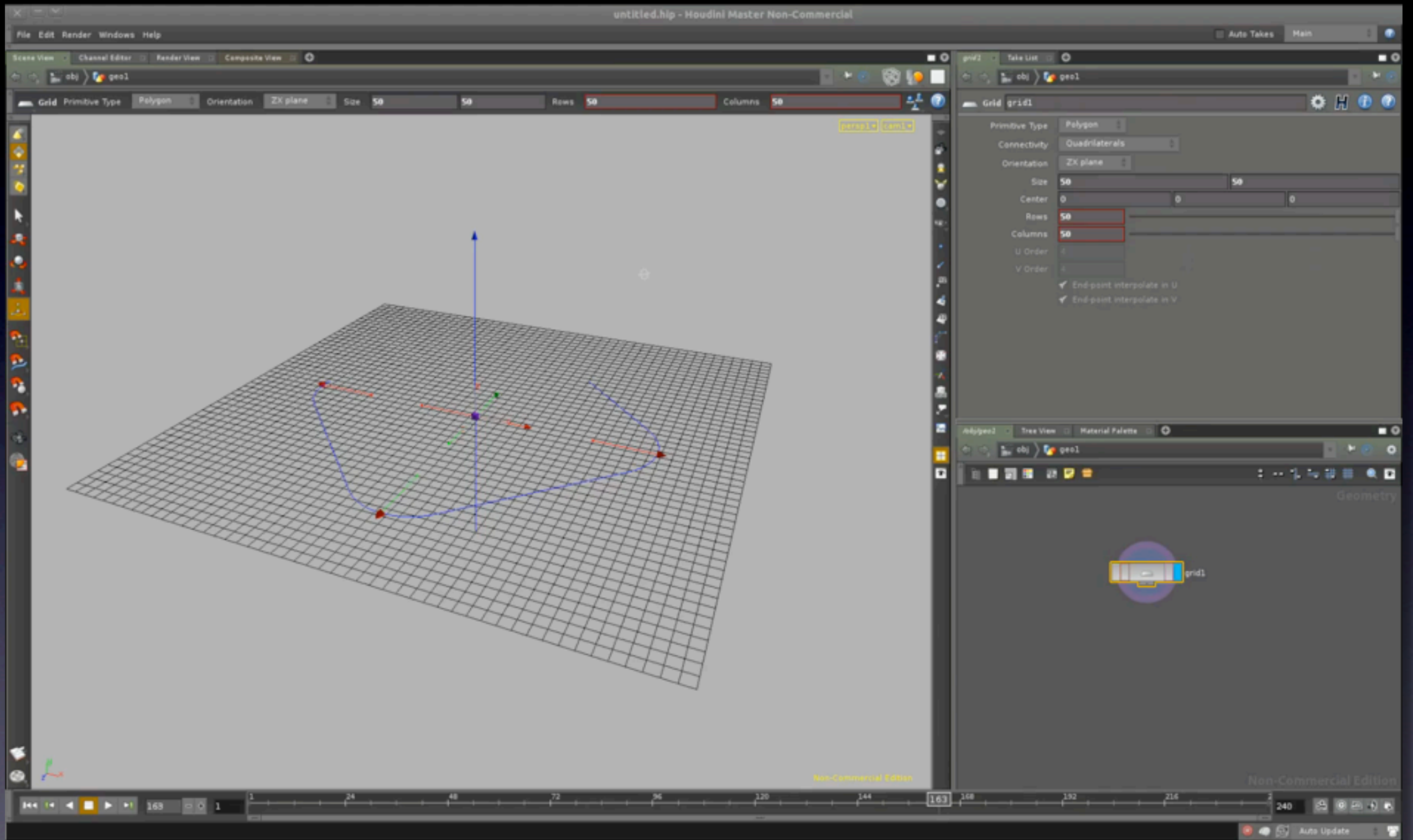
- Built & deployed with CMake:

```
find_package( PkgConfig REQUIRED )
pkg_check_modules( Cortex REQUIRED cortex )

include_directories( ${Cortex_INCLUDE_DIRS} )
link_directories( ${Cortex_LIBRARY_DIRS} )

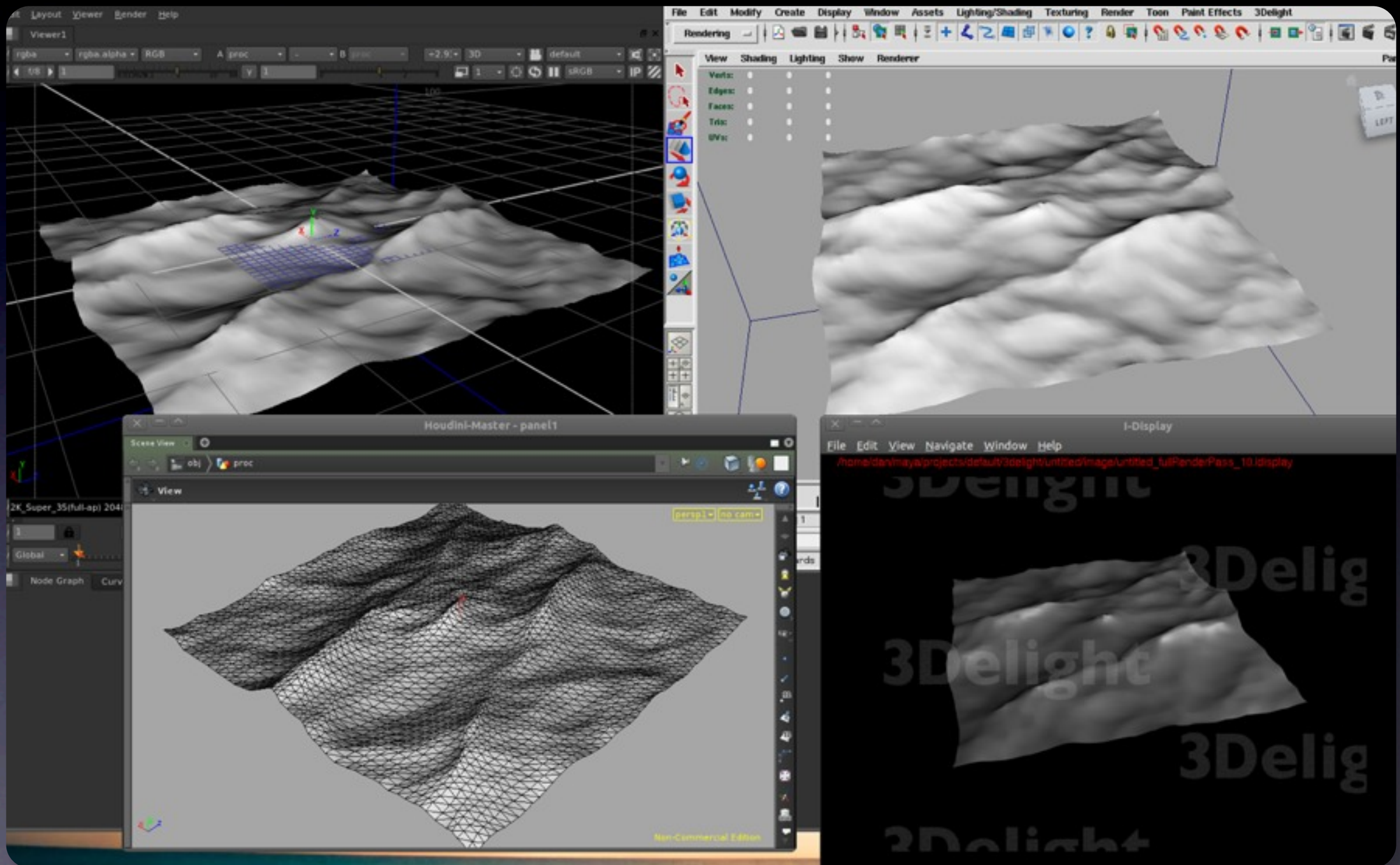
add_library( CortexOcean
  SHARED
  ${CMAKE_SOURCE_DIR}/src/OceanOp.cpp
)

target_link_libraries( CortexOcean
  ${Cortex_LIBRARIES}
  fftw3f
)
```



Duration: ~2 mins

- Runs unmodified in any Cortex host:



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danbethell / cortex-ocean

Watch Fork 1 1


Source Commits Network Pull Requests (0) Issues (0) Graphs Branch: master

Switch Branches (1) Switch Tags (0) Branch List

A port of the Houdini Ocean Toolkit to Cortex — [Read more](#) Downloads



HTTP Git Read-Only <https://github.com/danbethell/cortex-ocean.git> Read-Only access

Fixed problem with install op stub.

 Dan Bethell (author)
July 24, 2011

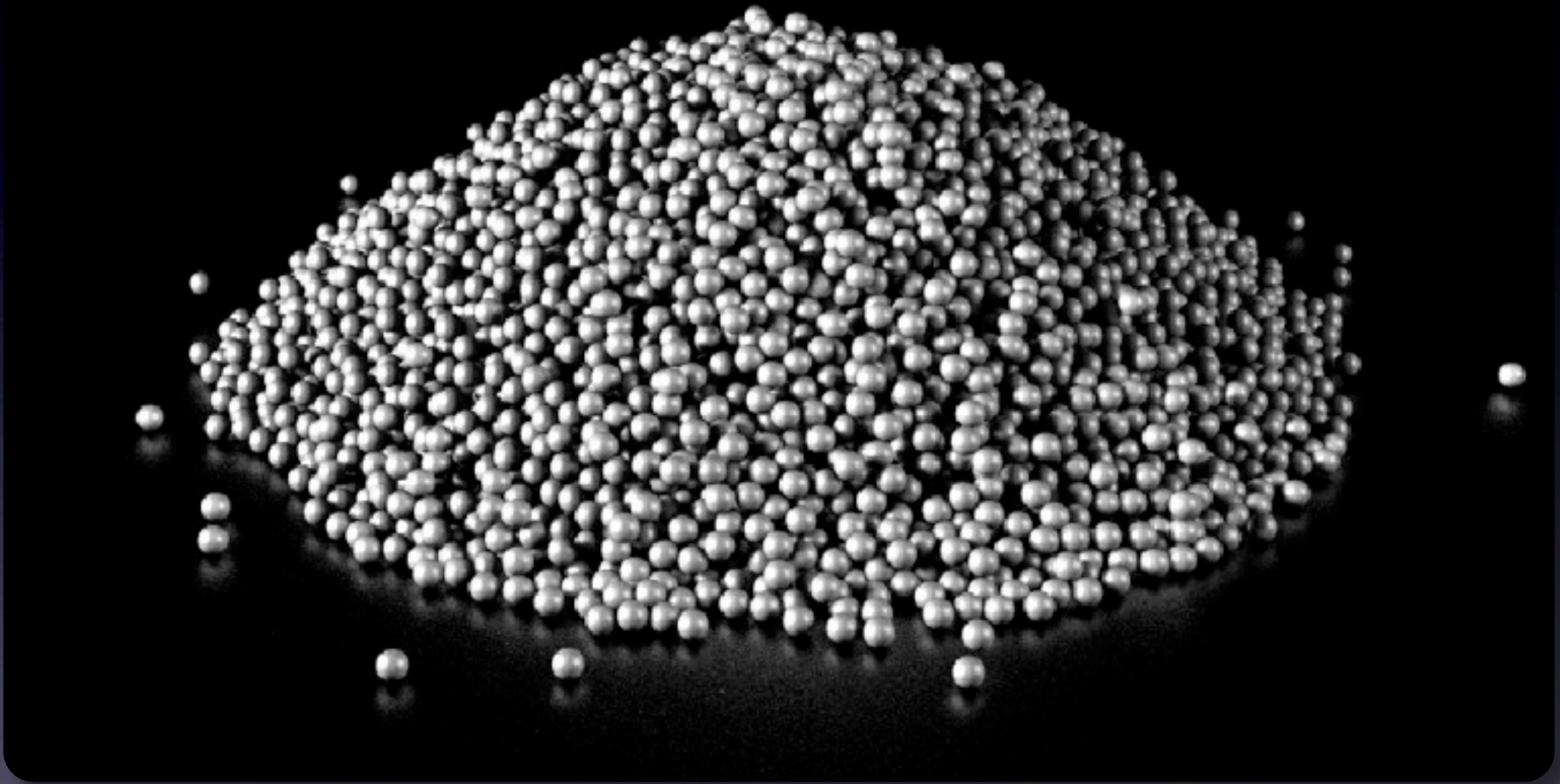
commit 6c03049b594f33b60efa
tree 8da4ef15306324f8922b
parent cd1ed52718032d538ded
parent bc608a04e7ccea0b8e4e

cortex-ocean /

name	age	message	history
 src/	July 20, 2011	early commit of cortex-ocean code. [Dan Bethell]	
 MakeLists.txt	July 24, 2011	Fixed problem with install op stub. [Dan Bethell]	

<http://github.com/danbethell/cortex-ocean>

Crumbs



Particle system implemented in C++/Cuda

- Passing data using Cortex:
 - Wrap custom type with `IECore::TypedData<>`.

```
// our custom type
namespace crumbs
{
    class Crumb
    {
        ...
    }
};
```

```
// wrapping for use with Cortex
namespace IECore
{
    typedef IECore::TypedData<crumbs::Crumb> CrumbsData;
    IE_CORE_DECLARE_PTR( CrumbsData );
}
```


- Passing our custom data between Ops:
 - Use the `IECore::ObjectParameter` type.

```
// define our Cortex parameter in our Op constructor
m_crumbsInput = new IECore::ObjectParameter( "input", "Crumbs input.",
    new crumbs::CrumbsData(), IECore::DataTypeId );

parameters()->addParameter( m_crumbsInput );
```

```
// in Op::doOperation extract the custom data
const CrumbsData *crumbs_data = operands->member<CrumbsData>( "input" );
const Crumb &crumb = crumbs_data->readable();
```


- Crumbs Types:

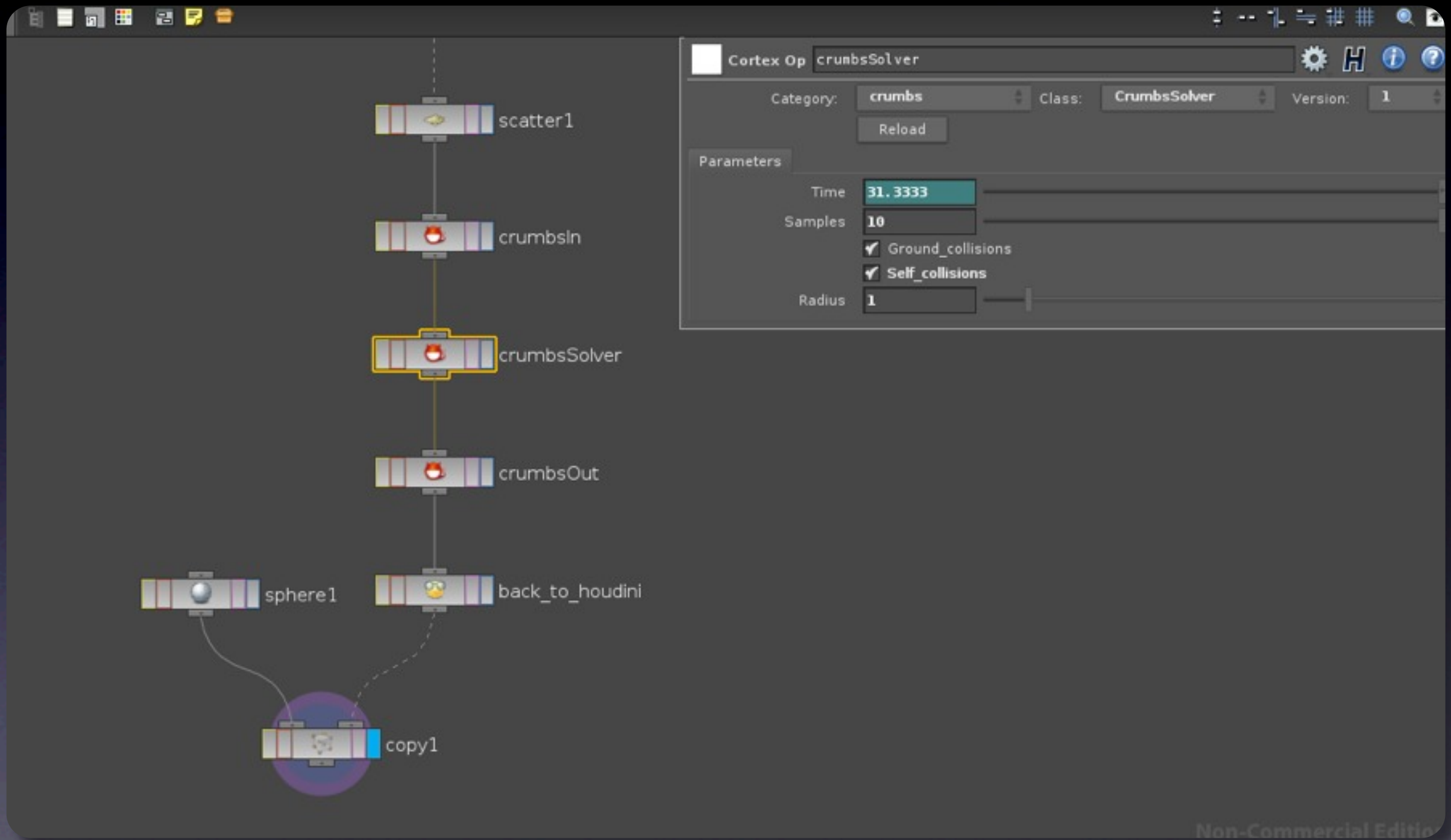
- Data

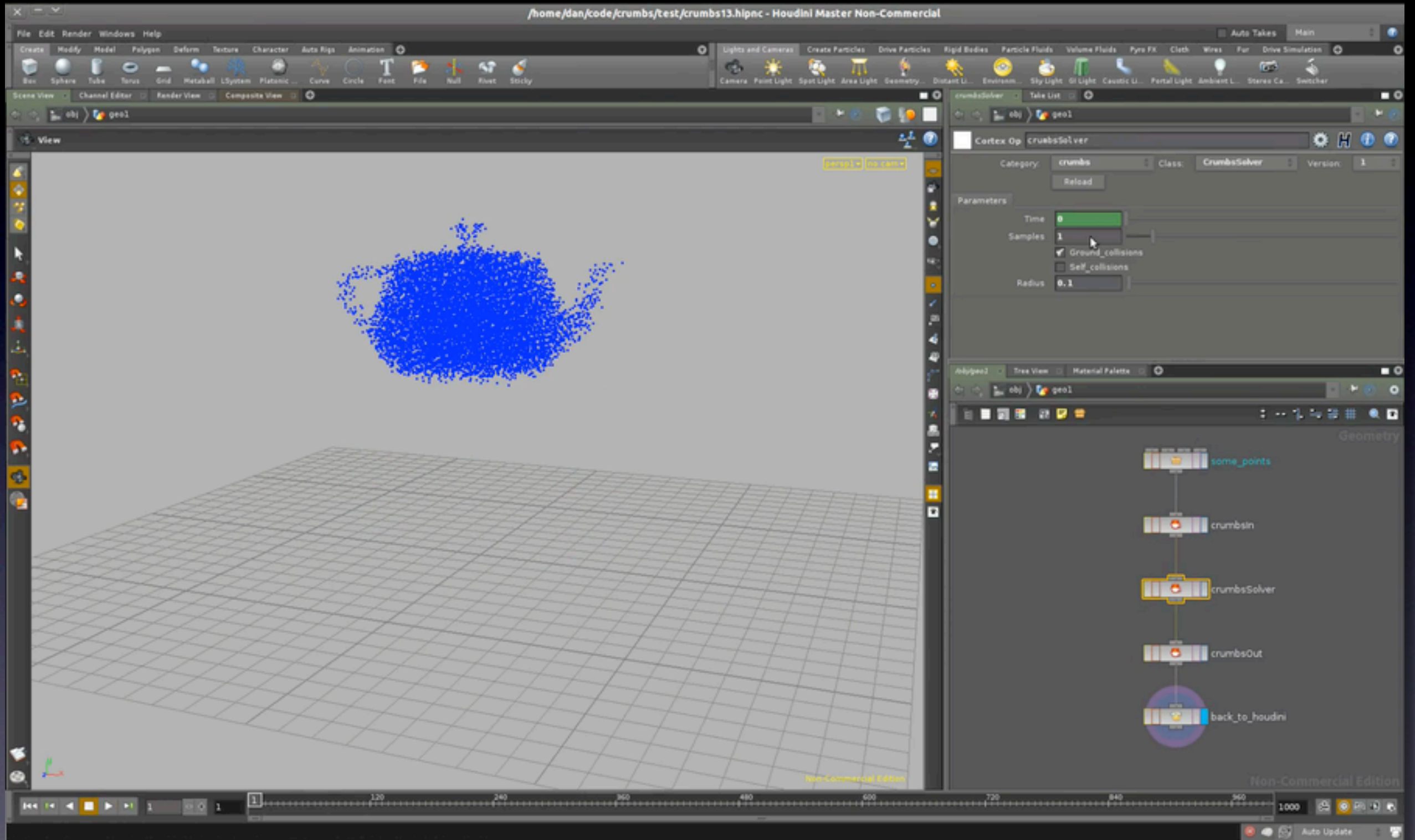
- crumbs::CrumbsData (Pass GPU info between Ops)

- Ops

- crumbs::CrumbsIn (Geometry Cortex->GPU)
- crumbs::CrumbsOut (Geometry GPU->Cortex)
- crumbs::CrumbsSolver (Simulation)

- Runs unmodified in any Cortex host:





Duration: ~ 1:30 mins

- Binding to Python is really quick:
 - IECorePython together with boost::python.

```
#include <boost/python.hpp>
#include <IECorePython/RunTimeTypedBinding.h>
#include "CrumbsIn.h"
#include "CrumbsSolver.h"
#include "CrumbsOut.h"

using namespace boost::python;

BOOST_PYTHON_MODULE( Crumbs )
{
    IECorePython::RunTimeTypedClass<crumbs::CrumbsIn>().def( init<>() );
    IECorePython::RunTimeTypedClass<crumbs::CrumbsSolver>().def( init<>() );
    IECorePython::RunTimeTypedClass<crumbs::CrumbsOut>().def( init<>() );
}
```


- Then... we can call our Ops from Python:

```
from IECore import *
from Crumbs import CrumbsIn, CrumbsOut, CrumbsSolver

# load points
points = Reader.create("myPoints.bgeo").read()

# upload, solve and download from gpu
gpu_in = CrumbsIn()( input=points )
gpu_solved = CrumbsSolver()( input=gpu_in, time=0.041 )
gpu_out = CrumbsOut()( input=gpu_solved )

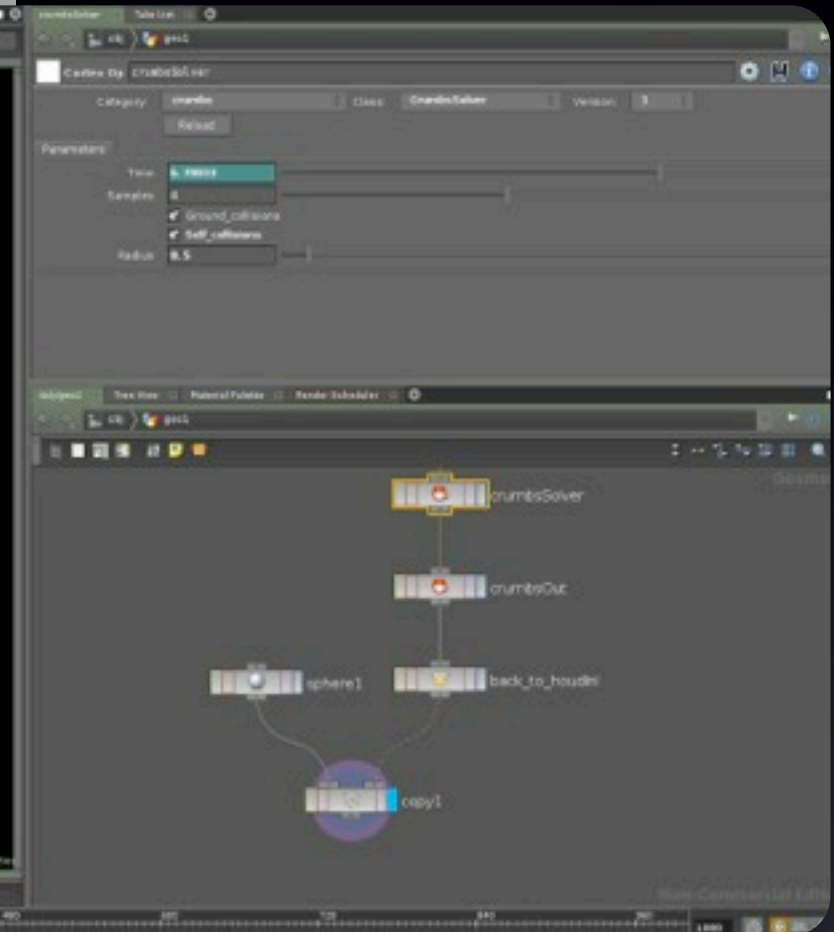
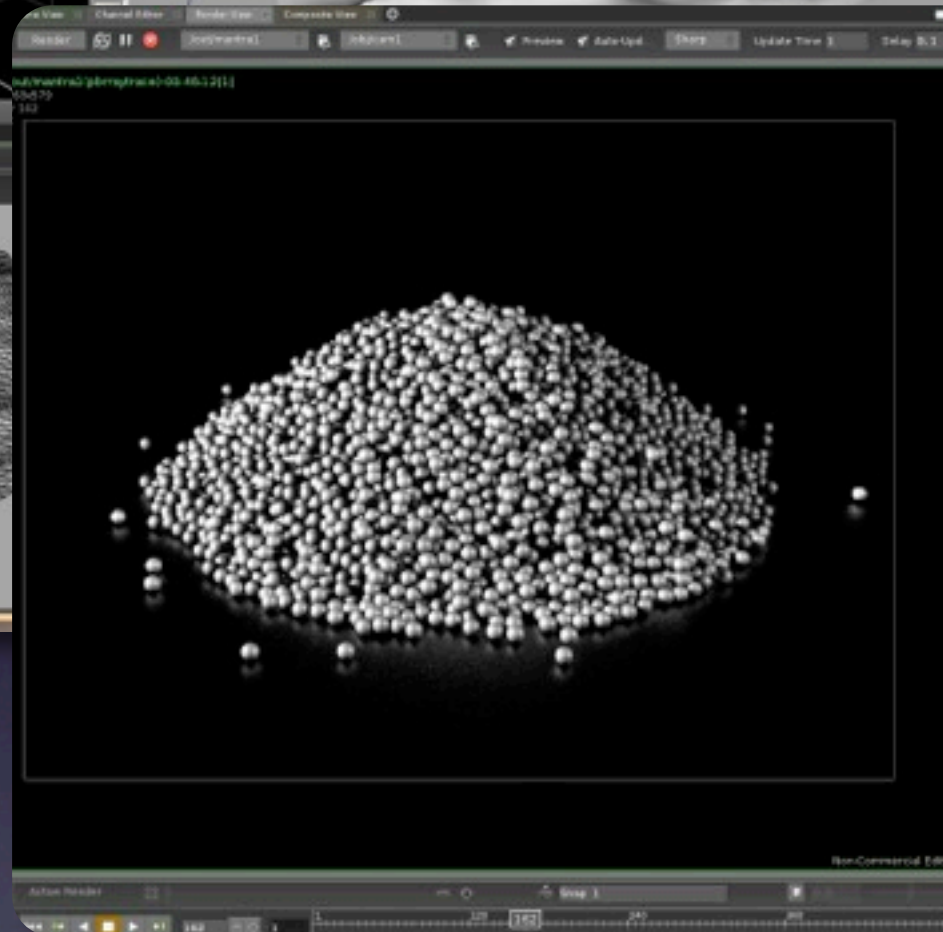
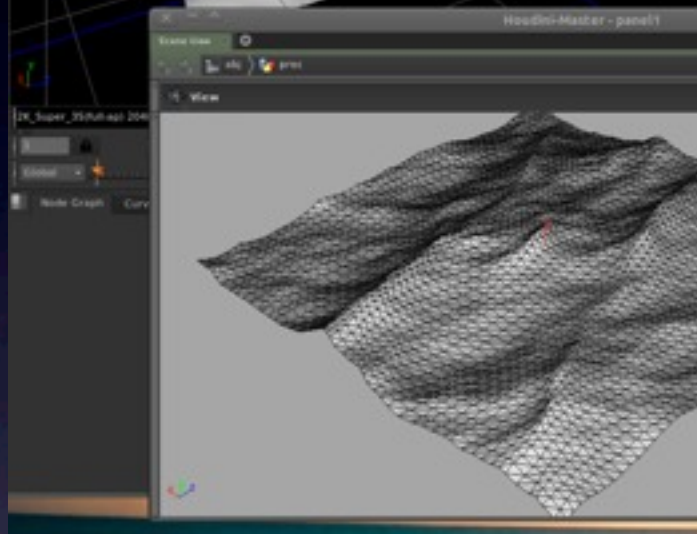
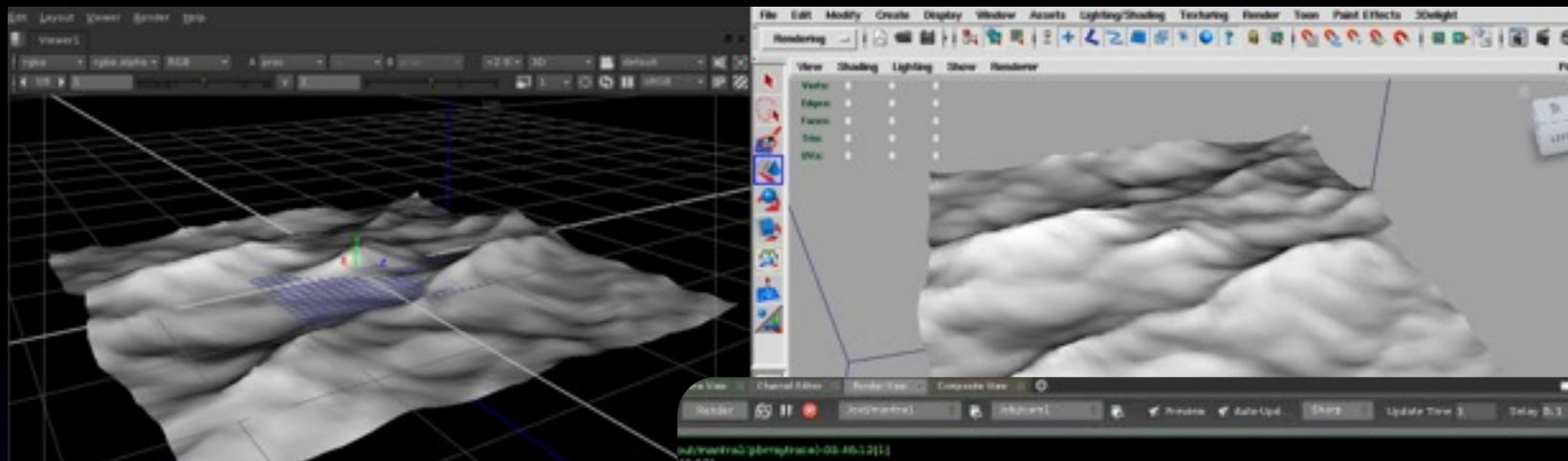
# save points
Writer.create( gpu_out, "particles.0001.bgeo" ).write()
```

Released as open-source soon...

<http://github.com/danbethell>

So, why use Cortex?

- Develop plugins outside application constraints.
- Straightforward to build & deploy against Cortex.
- Cortex API stable across major version.



danbethell@gmail.com

Nuke Integration

Paolo Berto, Jupiter Jazz

Nuke Integration

- Introduced in Cortex 6
- Hosting of procedurals and ops
- Lacking integration with built in renderer
- Wouldn't it be nice...

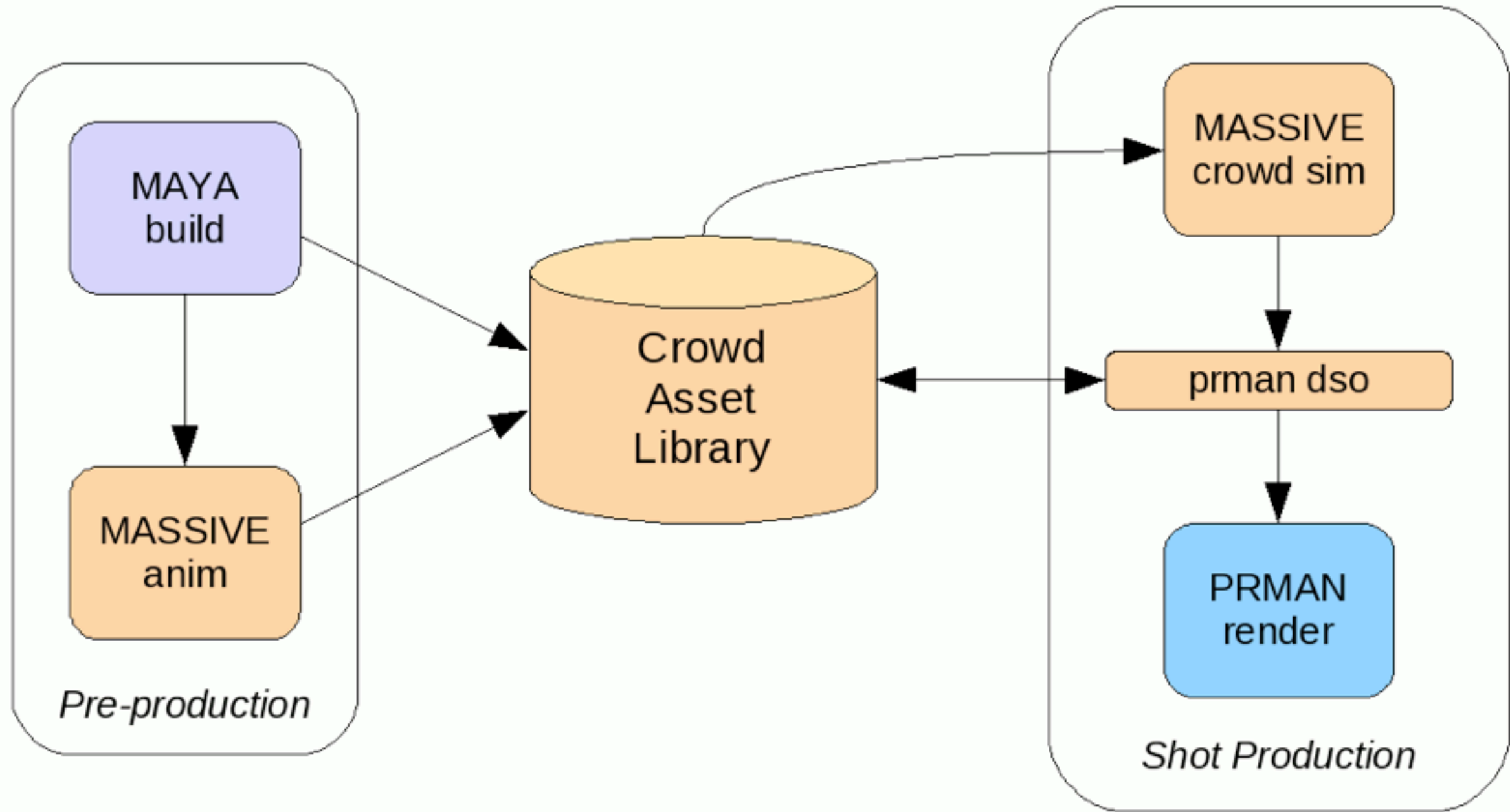
Oh No, Not Crowds Again

Using Cortex to Undo the Biggest Hack of All Time

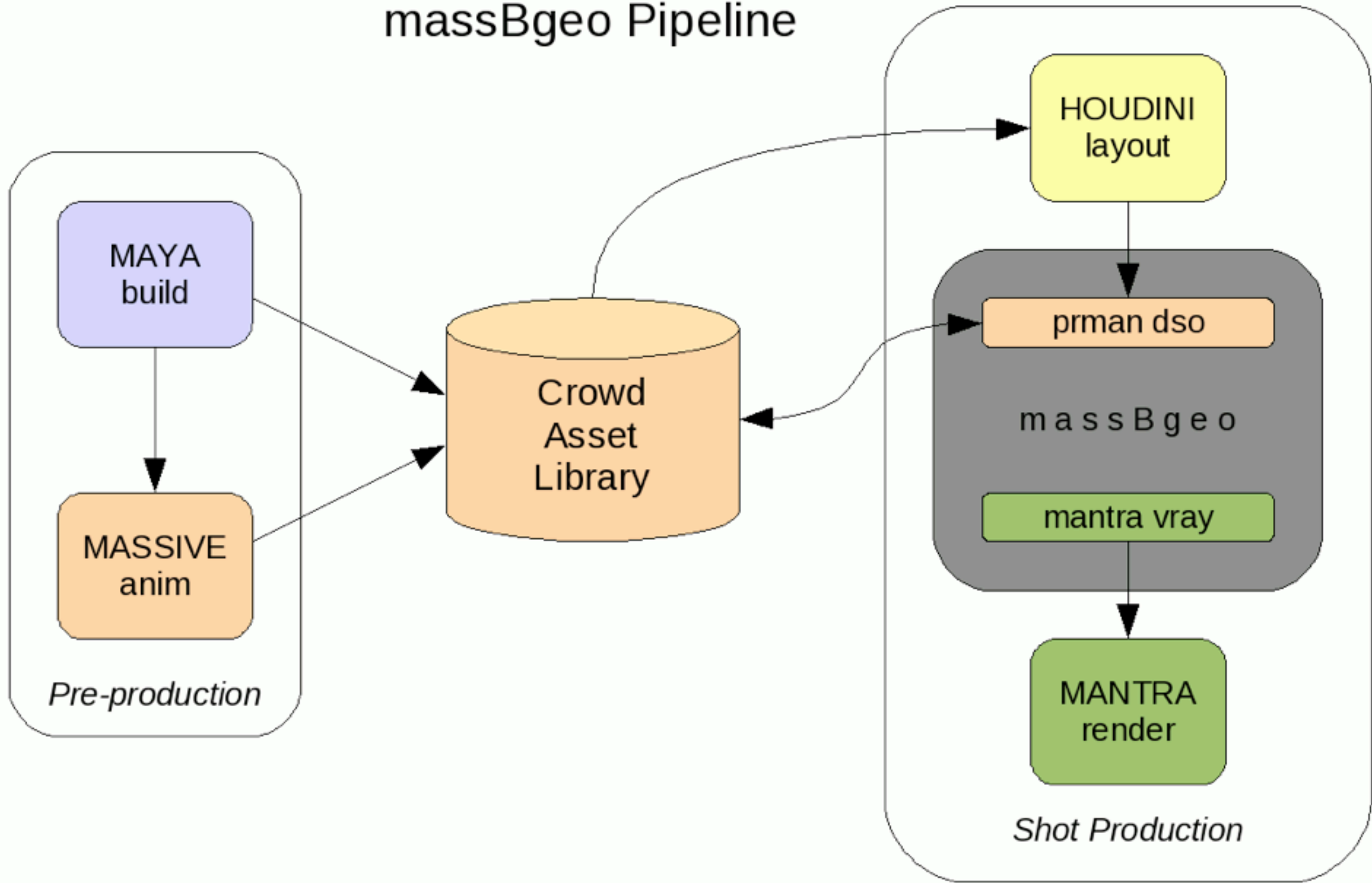
Ollie Rankin, Method



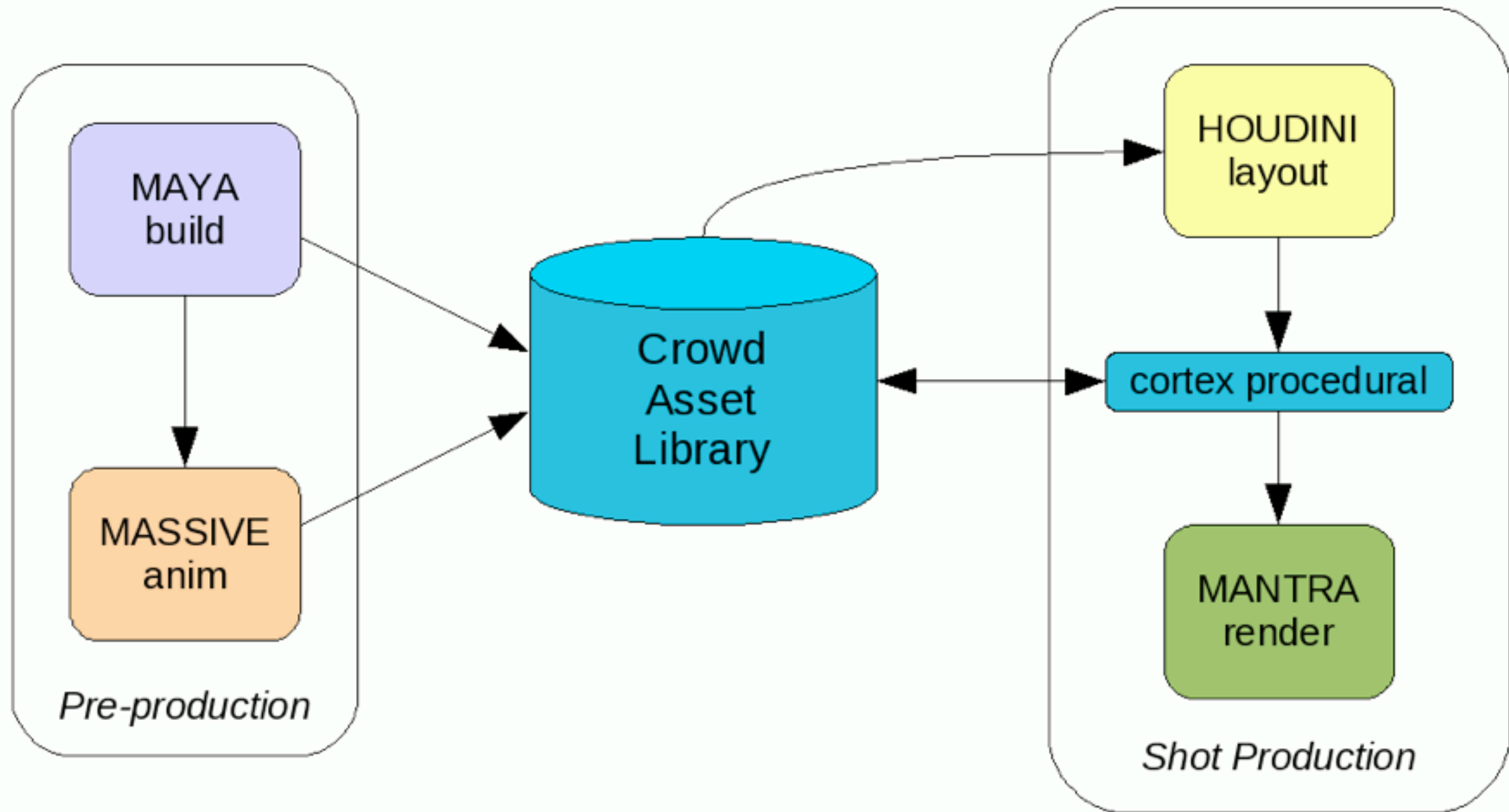
A Typical Massive Pipeline



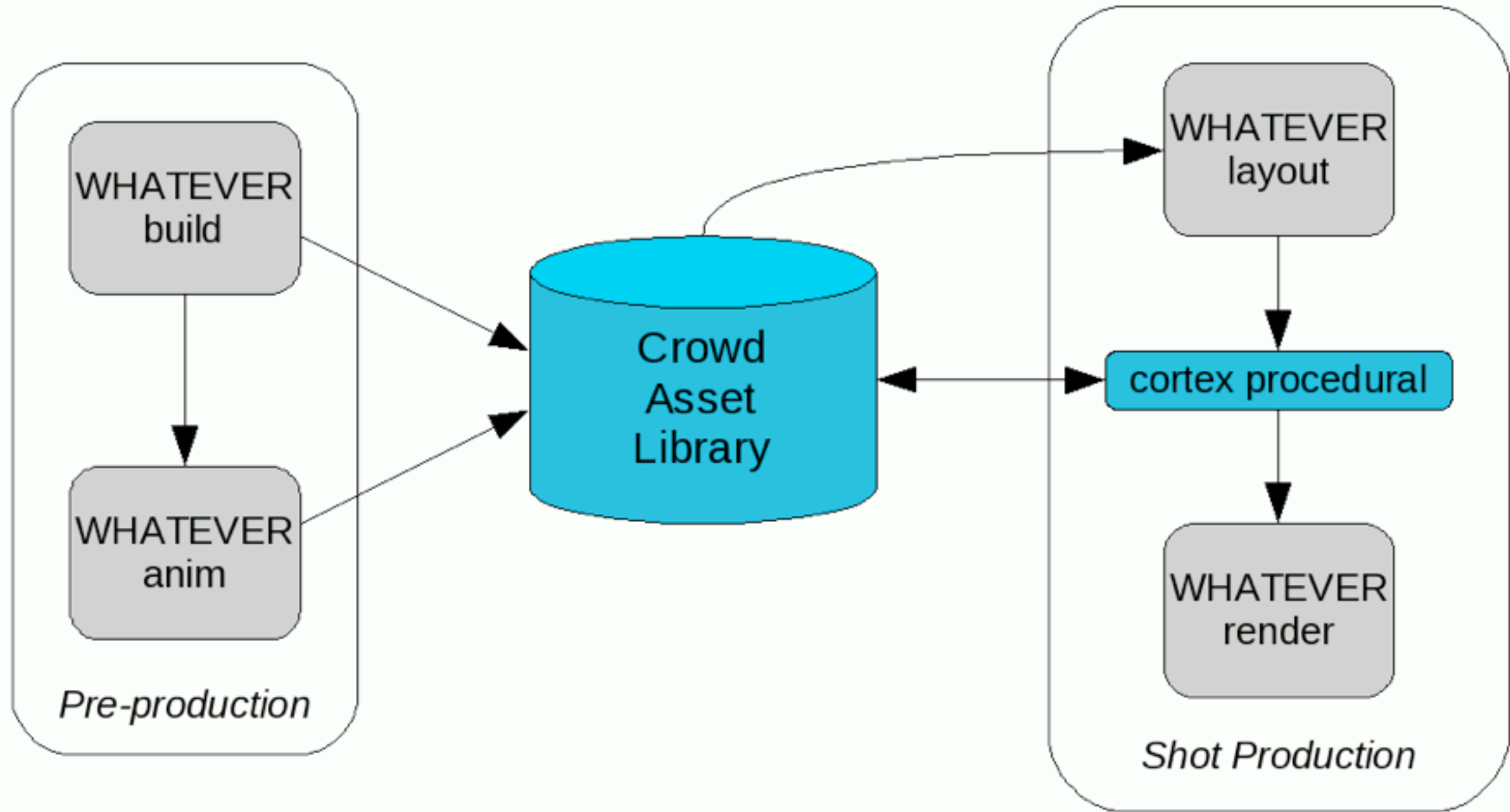
massBgeo Pipeline



First Gen Cortex Pipeline



Future Cortex Pipeline



Starting up with Cortex

Johannes Saam

fuelvfx



Situation at FUEL

- Growing from small to medium size
- Changing to a new Linux based pipeline
- Supporting as many applications as possible



Why Cortex

- Need all applications to be able to ‘talk’ to each other
- Platform for quick and flexible solutions
- Short development times and limited resources



Implications

- Compiling...
- Environment creation more complex
- Education required



Gains

- Solid base for your pipeline (find out how long it already exists)
- Support for free!
- Development for free!



First tests

- Tested mesh caching
- Cortex up to 6x faster than standard Maya caching
- Large meshes are handled really well
- File sizes on disk are a fraction
- First problem solved in only one hour of dev time



Plans

- Interchange Meshes / Particles
- Interchange Cameras
- Educate TD`s
- Contribute to the Nuke plugins
- Start Deep image support



Thanks

FUEL VFX

Pawel Olas

Max Stummer

Roy Mahli



Future Directions

John Haddon

When we have time...

- Better PRMan support
- More renderer backends
- Better documentation
- Binary downloads
- Windows builds
- Deep image support
-



Gaffer

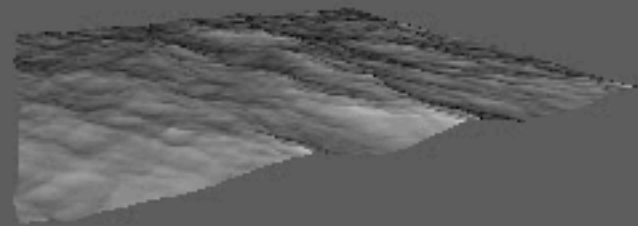
- Application framework
- Native Cortex host
- Work in progress



Gaffer continued...

- Dependency graph
- Undo/redo/cut/paste/load/save
- Files are Python scripts
- Python scripting is direct binding of C++ API
- UI toolkit wrapping Qt and OpenGL

Viewer



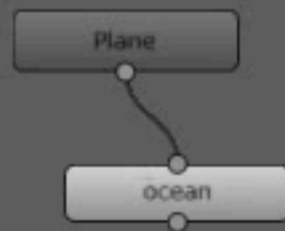
Node Editor

ocean

Waveheight	5.0
Seed	0
Chop	<input checked="" type="checkbox"/>
Choppiness	2.5
Damp	1.0
Windalign	2.0
Depth	200.0
Time	0.0



Graph Editor



Script Editor

```
timePlug = getChild( "ocean" )["parameters"]["time"]
```



code, examples, documentation

code.google.com/p/cortex-vfx

discussion

cortexdev@googlegroups.com